# Precision LCR Meter Instruction Manual 

Form 150566／A7

\author{

©QuadTech，Inc．， 2000 <br> 5 Clock Tower Place， 210 East <br> Maynard，Massachusetts，U．S．A． 01754 <br> February 2004 <br> | Telephone | $978-461-2100$ |
| :--- | :--- |
| Sales | $800-253-1230$ |
| Facsimile | $978-461-4295$ |
| Website | www．quadtech．com |

}

The material in this manual is for informational purposes only and is subject to change，without notice．QuadTech assumes no responsibility for any error or for consequential damages that may result from the misinterpretation of any procedures in this publication．

[^0]4Product will be marked with this symbol（ISO\＃3684）when it is necessary for the user to refer to the instruction manual in order to prevent injury or equipment damage．

モーニ Product marked with this symbol（IEC417）indicates presence of direct current．

Page 2 of 109

## Contents

Warranty ..... 7
Specifications ..... 9
Accessories ..... 11
Safety Precautions ..... 15
Condensed Operating ..... 17
Installation and Power Up
Selecting Test Conditions
Zeroing
Connection to Device Under Test
Initiating Tests
Introduction - Section 1
1.1 Unpacking/Inspection ..... 31
1.2 Product Overview ..... 31
1.3 Front Panel Description ..... 32
1.4 Rear Panel Description ..... 34
1.5 Installation ..... 35
1.5.1 Dimensions ..... 35
1.5.2 Instrument Positioning ..... 35
1.5.3 Power Requirements ..... 35
1.5.4 Safety Inspection ..... 37
Operation - Section 2
2.1 Terms and Conventions ..... 39
2.2 Power Up ..... 41
2.3 Program/Setup Procedure (Test 1-25) ..... 41
2.3.1 Primary Parameter. ..... 42
2.3.2 Secondary Parameter ..... 45
2.3.3 Frequency ..... 46
2.3.4 Amplitude ..... 46
2.3.5 Bias Voltage ..... 47
2.3.6 Range Select ..... 48
2.3.7 Accuracy ..... 51
2.3.8 Delay ..... 53
2.3.9 No. to Average ..... 54
2.3.10 Primary Nominal ..... 55
2.3.11 Bin Type ..... 56
2.3.12 Secondary Nominal ..... 59

## Contents (continued)

2.3.13 Load Correction ..... 60
2.3.14 Primary Load Correction. ..... 61
2.3.15 Secondary Load Correction ..... 61
2.4 Program/Sequence (Test S1-S9) ..... 62
2.5 Utility Functions ..... 64
2.5.1 Perform Calibration ..... 65
2.5.2 Keypad Lockout ..... 69
2.5.3 Display Type ..... 72
2.5.4 Numeric Format ..... 73
2.5.5 Trigger Source. ..... 74
2.5.6 Source Impedance ..... 74
2.5.7 RS-232 Baud Rate ..... 75
2.5.8 IEEE488 Address ..... 75
2.5.9 Clear All Tests ..... 76
2.5.10 Leveling ..... 76
2.5.11 Cable Comp ..... 77
2.5.12 Frequency Edit Type ..... 77
2.5.13 Median ..... 78
2.5.14 Distortion ..... 78
2.5.15 Serial Number ..... 79
2.5.16 Software Version ..... 79
2.6 Error Messages ..... 79
Interface - Section 3
3.1 General ..... 81
3.2 Remote I/O ..... 81
3.3 RS-232 Interface ..... 83
3.4 IEEE-488.2 Interface. ..... 84
3.4.1 General ..... 84
3.4.2 IEEE-488 Connections ..... 85
3.4.3 IEEE-488 \& RS-232 Commands ..... 86
3.4.4 Formats ..... 92

## Contents (continued)

Theory - Section 4
4.1 Introduction ..... 95
4.1.1 Description of 1920 Precision LCR Meter ..... 95
4.1.2 Block Diagram ..... 97
4.2 Principle Functions ..... 99
4.2.1 Fundamental Measurement ..... 99
4.2.2 Sine Wave and Sampling Pulse Generator ..... 100
4.2.3 Digitization ..... 100
Service \& Calibration - Section 5
5.1 General ..... 103
5.2 Instrument Return ..... 103
5.3 Calibration ..... 103
5.3.1 1920 Verification Procedure ..... 103
5.3.2 1920 Verification Data Sheet ..... 106
5.4 Diagnostics ..... 109
5.4.1 Start-up Diagnostics ..... 109

Page 6 of 109

## Warranty

QuadTech warrants that Products are free from defects in material and workmanship and, when properly used, will perform in accordance with QuadTech's applicable published specifications. If within one (1) year after original shipment it is found not to meet this standard, it will be repaired, or at the option of QuadTech, replaced at no charge when returned to a QuadTech service facility.

Changes in the Product not approved by QuadTech shall void this warranty.

QuadTech shall not be liable for any indirect, special or consequential damages, even if notice has been given of the possibility of such damages.

This warranty is in lieu of all other warranties, expressed or implied, including, but not limited to any implied warranty or merchantability or fitness for a particular purpose.

## SERVICE POLICY

QuadTech policy is to maintain product repair capability for a period of at least five (5) years after original shipment and to make this capability available at the then prevailing schedule of charges.

Page 8 of 109

## Specifications



# Specifications (continued) 

| Results Format: | Engineering Numeric <br> Deviation from Nominal of Primary Parameter \% Deviation from Nominal of Primary Parameter No Display (for maximum throughput) |
| :---: | :---: |
| Interfaces: | IEEE-488, RS-232, Handler I/O |
| Measurement Delay: | 0 to 100 s , programmable in 10 ms steps |
| Averaging: | 1 to 1000, programmable |
| Mechanical: | Bench Mount (optional rack mount flanges available, 2000-16) |
| Dimensions: | ( w x h x d): $17 \times 5.25 \times 16 \mathrm{in}, 432 \mathrm{x} 133 \mathrm{x} 406 \mathrm{~mm}$ |
| Weight: | 15lbs (8kg) net, 211bs (9.9kg) shipping |
| Environmental: | MIL-T28800E, Type 3, Class 5, Style E \& F <br> Operating: 0 to $+50^{\circ} \mathrm{C}$ Storage: -40 to $+71^{\circ} \mathrm{C}$ <br> Humidity: $<75$ for $<+40^{\circ} \mathrm{C}$ operating <br> Altitude: <2000m, Installation Category 1 Pollution Degree 1 |
| Power: | 100 to $240 \mathrm{VAC} 50-60 \mathrm{~Hz} \quad 100 \mathrm{~W}$ max |

## Accessories

## Accessories Included

| Item | Quantity | QuadTech P/N |
| :--- | :--- | :--- |
| AC Power Cord | 1 | $4200-0300$ |
| Power Line Fuse (installed in instrument) | 1 | 520049 |
| Instruction Manual | 1 | 150566 |
| Calibration Certificate | 1 | N/A |

Accessories/Options Available

| Item | Quantity | QuadTech P/N |
| :--- | :--- | :--- |
| Axial/Radial Component Test Fixture | 1 | $1700-01$ |
| Axial/Radial Remote Test Fixture | 1 | $1700-02$ |
| 4 BNC Connectors to 2 Kelvin Clip Lead Set | 1 | $1700-03$ |
| 4 BNC Connectors to 4 Banana Plugs, w/alligator clips | 1 | $1700-04$ |
| 4 BNC Connectors to 2 Chip Component Tweezers | 1 | $1700-05$ |
| 4 BNC to 4 BNC Cable Set (1 meter) | 1 | $7000-01$ |
| 4 BNC to 4 BNC Cable Set (2 meters) | 1 | $7000-02$ |
| Low Voltage Chip Component Test Fixture | 1 | $7000-07$ |
| Rack Mount Flanges | 1 | $2000-16$ |



Figure A-1
1700-01 Axial/Radial Component Test Fixture

## Accessories (Continued)



Axial Lead Adapter Shorting Bar Rotated 90 degrees

Figure A-2
1700-02 Axial/Radial Remote Test Fixture


Figure A-3
1700-03 BNC (4) Connectors to 2 Kelvin Clip Lead Set


Figure A-4
1700-04 BNC (4) Connectors to Banana Plugs (4)

## Accessories (Continued)



Figure A-5
1700-05 BNC (4) Connectors to 2 Kelvin Clip Lead Set


Figure A-6
7000-01 BNC (4) to BNC (4) Cable Set, 1 meter 7000-02 BNC (4) to BNC (4) Cable Set, 2 meters


Figure A-7
7000-07 Low Voltage Chip Component Test Fixture

## Accessories (Continued)



Figure A-8
2000-16 Rack Mount Flanges
The 2000-16 Rack Mount Flanges (quantity 2, left and right) are used as dress panels to adapt the 1920 to the standard 19 inch rack width. THESE FLANGES SHOULD NOT BE USED AS SOLE MOUNTING SUPPORT OF THE 1920 in rack mount applications. Chassis guides or other mechanical support is required to support the instrument. Chassis guides are available from:

Amco Engineering Company
3801 North Rose Street
Schiller Park, Illinois 60176-2190
Telephone (847) 671-6670
Installation

| WARNING |
| :---: |
| MAKE SURE THE UNIT HAS BEEN DISCONNECTED FROM ITS AC POWER SOURCE FOR |
| SEVERAL MINUTES BEFORE PROCEEDING. |

1) Remove the 4 screws and washers, two each side on the front side cover.
2) Mount the two flanges using the screws and washers previously removed. Note that the flange with the cutout is to be mounted on the right so as not to cover up the side vent holes. Refer to the figure below.


Figure A-9: Flange Mounting

## Safety Precautions

The 1920 Precision LCR Meter can provide an output voltage to 1.0 V AC and 2.0 V DC to the device under test (DUT). Although the 1920 unit is designed with full attention to operator safety, serious hazards could occur if the instrument is used improperly and these safety instructions are not followed.

1. The 1920 Precision LCR Meter unit is designed to be operated with its chassis connected to earth ground. The instrument is shipped with a three-prong power cord to provide this connection to ground. This power cord should only be plugged in to a receptacle that provides earth ground. Serious injury can result if the 1920 Precision LCR Meter is not connected to earth ground.
2. Tightly connect the 4 BNC test cables or test fixture to the front panel connectors. If this is not done improper measurements are possible, or an electrical shock to the operator could result if the DUT is touched.
3. Never touch the test leads, test fixture or DUT in any manner (this includes insulation on all wires and clips) when the bias current is applied and the BIAS ON light is on.
4. Before turning on the 1920 Precision LCR Meter unit, make sure there is no device (DUT) or fixture connected to the test leads.
5. Before touching the test leads or device under test make sure:
a) Any capacitive device has had enough discharge time.
b) The green BIAS ON LED is NOT lit.
6. In the case of an emergency, turn OFF the POWER switch using a "hot stick" and disconnect the AC power cord from the wall. DO NOT TOUCH THE 1920 INSTRUMENT.
7. When the 1920 Precision LCR Meter instrument is used in remote control mode, be extremely careful. Output voltage or current can be turned on and off with an external signal.

Page 16 of 109

## Condensed Operating Instructions

## Start-Up

The 1920 Precision LCR Meter can be operated from a power source between 90 and 250 VAC at a power line frequency of 50 to 60 Hz . The unit is shipped with a 2.5 A fuse in place for 90 to 250 V operation. Refer to paragraph 1.5.3 for fuse location and/or replacement.

The 1920 Precision LCR Meter is designed to be operated with its chassis connected to earth ground, a 3-prong power cored is provided with the unit to make this connection. Connect one end of the power cord to the instrument's rear panel power receptacle and the other end to the proper ac power source.

Press the Power button on the front panel to the (1) position to apply power. The power can be switched off at any time by pressing the this front panel switch to the (0) position.

## Power Up

Press power switch to On (1)

Unit initializes
through
Steps 1 to 11

| QuadTech |
| :---: |
| Model 1920 V1.4 |

Displays software version


## Condensed Operating Instructions

## Programming Test Conditions

Press the UP or DOWN arrow to selecttest \# (location where test conditions are stored).

UP $\quad$| 1 | Ls Rs 1.000 kHz |
| :--- | :--- |
| 1.000 V No Bias Auto High |  |

Test \# (1-30)
Sequence Test \# (S1-S10)
Refer to paragraph 2.4

Press PROGRAM to enter programming mode
[PROGRAM]

| Prim Param Program <br> Automatic |
| :--- |

Press [PROGRAM] at any time to exit programming mode.

## Measured Parameters

Press the UP or DOWN arrow to selectmeasurement parameter
UP
1 Prim Param Program
Automatic, Ls, Lp, Rs, Rp, Cs, $\mathrm{Cp}, \mathrm{DF}, \mathrm{Q}, \mathrm{Z}, \mathrm{Y}, \mathrm{P}, \mathrm{ESR}, \mathrm{Gp}$, Xs, Bp, V, I, DCV, DCR, DCI

Press the RIGHT arrow to selectsecondary measurement parameter

Right \begin{tabular}{l}

| 1 Sec Param Program |
| :--- |
| No Secondary param |$\quad$| Not shown if Primary |
| :--- |
| Parameter is set to Automatic | <br>

\hline
\end{tabular}

Press the UP or DOWN arrow to enter secondary measurement parameter

UP $\triangle$\begin{tabular}{lll}

| 1 | Sec Param Program |
| :--- | :--- |
| $Q$ |  | | Ls, Lp, Rs, Rp, Cs, Cp, DF, Q, |
| :--- |
| Z, Y, P, ESR, Gp, Xs, Bp, V, I, | <br>

No secondary parameter
\end{tabular}

## Frequency

Press the RIGHT arrow to selectest frequency

Right $>$\begin{tabular}{|l|l}

| 1 Frequency Program |
| :--- |
| 20.000 Hz | \& | Not shown if Primary |
| :--- |
| Parameter is set to DCV, DCR |
| or DCI |

\end{tabular}

Press the UP or DOWN arrow to entertest frequency parameter

| $1 \quad$ Frequency | Program |
| :--- | :--- |
| 1.0000 kHz |  |

$20 \mathrm{~Hz}-1.0 \mathrm{MHz}, 15$ steps or 20 Hz - 1.0 MHz , continuous Refer to paragraph 2.3.3

## Condensed Operating Instructions

## Amplitude

Press the RIGHT arrow to selectamplitude of voltage

Right
1 Amplitude Program
20.00 mV

Press the UP or DOWN arrow to changeamplitude value
UP

1. Amplitude Program 1.0000 V
$20.00 \mathrm{mV}-1.0000 \mathrm{~V}$ in 5 mV steps

## Bias Voltage

Press the RIGHT arrow to selectbias voltage

Right

| 1 |
| :--- |
| 1.00 mV | Bias Voltage Program

Not shown if Primary Parameter is set to DC

Press the UP or DOWN arrow to changebias voltage value
UP

| 1 Bias Voltage Program |
| :--- | :--- |
| Off |

Off, $1.00 \mathrm{mV}-2.000 \mathrm{~V}$
in 1 mV steps

## Measure Range

Press the RIGHT arrow to selectmeasurement range

Right

| 1 Range Select | Program |
| :--- | :--- |
| Lock 200 mA , any F $\quad 1.0 \mathrm{~V}$ |  |

Press the UP or DOWN arrow to changemeasurement rangevalue
UP $\quad 1 \quad$ Range Select Program Auto, Hold or 27 individual Lock 2.6uA, $\mathrm{F}<=10 \mathrm{k} \quad 16 \mathrm{mV}$ ranges (45 for DC), refer to paragraph 2.3.6

## Accuracy

Press the RIGHT arrow to selectmeasurement accuracy

Right

```
1 Accuracy Program
Low (40ms test)
```

Press the UP or DOWN arrow to changemeasurement accuracyvalue

UP

1 Accuracy Program High (1 second test)

High, Medium, Low or No Display

## Condensed Operating Instructions

## Delay

Press the RIGHT arrow to select delay time


Press the UP or DOWN arrow to change delay time value UP

## Averaging

Press the RIGHT arrow to select number to average

Right


Press the UP or DOWN arrow to change number to average value
UP


## Primary Nominal

Press the RIGHT arrow to select primary nominal

Right \begin{tabular}{|ll}

| Pri Nominal |
| :--- |
| 1.0000 H | \& (START $=$ get) $\quad$| Not shown if Primary |
| :--- |
| parameter is set to Automatic | <br>

\hline
\end{tabular}

Press the UP or DOWN arrow to change primary nominal value


Range of values and units depend on primary parameter selected at first step

## Condensed Operating Instructions

## Binning (Primary Parameter)

Press the RIGHT arrow to select bin type

Right

1 Bin Type Program Off

Not shown if Primary Parameter is set to Automatic

Press the UP or DOWN arrow to changebin type

UP

Press the RIGHT arrow to selectbinning HIGH limit value

Righ

| $1 \quad$ Bin 1 HiLim | Program |
| :--- | :--- |
| 100.00 mH |  |

Not shown if Binning is set to Off for all bins

Press the UP or DOWN arrow to changebinning HIGH limit value
UP

| 1 Bin 1 HiLim | Program |
| :--- | :--- |
| 110.0 mH |  |

Off, or limit in value and units for Absolute Limit, or value in \% for \% deviation (-100\%-+200\%)

Press the RIGHT arrow to selectbinning LOW limit value

Right

| 1 Bin 1 LoLim | Program |
| :--- | :--- |
| 100.00 mH |  |

Press the RIGHT arrow to changebinning LOW limit value

UP




Bins 2 through 10 !

Off, or limit in value and units for Absolute Limit, or value in \% for \% deviation (-100\%-+200\%)

Limits can be set to Off at the point where Hi and Lo values converge

Press the RIGHT arrow to select Hi and Lo limits for Bins 2-10

Right

```
1 Bin 10 LoLim Program
100.00 mH
```

Press the UP or DOWN arrow to changeHi and Lo limits for Bins 2-10

UP

| 1 Bin 10 LoLim Program |
| :--- | :--- |
| 50.00 mH |

Off, or limit in value and units for Absolute Limit, or value in \% for \% deviation (-100\%-+200\%)

## Condensed Operating Instructions

## Secondary Nominal

Press the RIGHT arrow to selectsecondary nominalvalue

Right
1 Sec Nominal Program

Not shown if Primary Parameter is set to Automatic

Press the UP or DOWN arrow to changesecondary nominalvalue

UP

| $1 \quad$ Sec Nominal Program |
| :--- | :--- |
| 10.000 |

Off, or range of values and units that depend on secondary parameter

## Binning (Secondary Parameter)

Press the RIGHT arrow to selectsecondary HIGH limit value


Not shown if Primary Parameter is set to Auto or Binning is set to Off for all bins

Press the UP or DOWN arrow to changesecondary HIGH limitvalue

UP
1 Sec HiDev Program
Off, or range of value and units dependent on the secondary parameter

Press the RIGHT arrow to selectsecondary LOW limit value

Right

1. Sec LoLim Program
1.0000

Press the RIGHT arrow to changesecondary LOW limit value

UP


Off, or range of value and units dependent on the secondary parameter

## Condensed Operating Instructions

## Load Correction

Press the RIGHT arrow to selectload correction

Right
LoadCorrect $(S T A R T=G E T)$
Off

Not shown if Primary parameter is set to Automatic

Press the UP or DOWN arrow to changeload correction value
UP
LoadCorrect $\quad(S T A R T=G E T)$
Measure $)$
Off, On

Press [START] to measure Load Correction based on primary and secondary nominals with device connectedOR

Press the RIGHT arrow to select primary load correction

Right $\quad$\begin{tabular}{l}

| 1 Pri Load Corr |
| :--- |
| 8.0000 mH | <br>

\hline
\end{tabular}

Press the UP or DOWN arrow to changeprimary load correctionvalue


Press the RIGHT arrow to select secondary load correction

Right

| 1 Sec LoadCorr | Program |
| :--- | :--- |
| 50.000 |  |

Press the UP or DOWN arrow to changesecondary load correctionvalue UP

| 1 Sec LoadCorr | Program |
| :--- | :--- |
| 1.100 |  |

Range of values and units depend on primary parameter selected at first step

Press the RIGHT arrow to return display toReady Mode

Right

| 1 Ls | Rs | 1.0000 kHz |  |
| :--- | :--- | :--- | :--- |
| 1.0000 V | No Bias | Auto | High |

Ready Mode showing first parameter

## Condensed Operating Instructions

## Programming Tester Utility Functions

Tester functions are accessed through the UTILITY mode.

| [UTILITY] | Cal with 1 M Cable <br> Cal Due: $1 / 10 / 2001$ |
| :--- | :--- |

Press [UTILITY] at any time to exit programming mode.

## Perform Calibration/Zeroing

Press the RIGHT arrow to skip Open/Short and go to Keypad Lockout with indicated cable length
Right
Cal with 1M Cable
Cal Due: $1 / 10 / 2001$
Indicates due date of next annual calibration

Press the UP or DOWN arrow to select Open/Short Calibrationtype
Quick Short Cal, Quick Open Cal,
UP

| 1 | Prim Param |
| :--- | :--- |
| Ls |  |$\quad$ Program Quick Short/Open Cal, Short Cal, Open Cal, Short/Open Full Cal

NOTE: "Quick Cal is not an option if test is a sequence test (S1-S9).
NOTE: "Open Cal" and "Quick Open Cal" are not an option if test is a DC test (DCR, DCV, DCI)
To connect Test Leads refer to "Connection to Device Under Test" paragraph that follows.

Right

Connect OPEN standard Press START to continue

Press [STOP] at any time to exit Cal routine

Connect Test Leads in OPEN configuration


Press the [START] to initiate open calibration measurement

| C: $1 \quad$ 9: F1 I5 V2 |
| :--- | :--- |
| Open correction |

Open Correction factor

## Condensed Operating Instructions

Connect SHORT standard Press START to continue.

Remove Open.

Connect Test Leads in SHORT configuration


Kelvin Leads Clipped Together
Press the [START] to initiate short calibration measurement
[START]


Calibration Complete Press START to continue
[START]

$$
\begin{aligned}
& 1 \mathrm{Ls} \text { Rs } 1.0000 \mathrm{kHz} \\
& 1.000 \mathrm{~V} \text { No Bias Auto High }
\end{aligned}
$$

OR
[UTILITY]

Cal with 1M Cable
Cal Due: 1/10/2001

Ready Mode
Short Correction factor

Ready

To program other Tester Utility Functions

Press the RIGHT arrow to program otherUTILITY functions

## Keypad Lockout

Press the UP or DOWN arrow to changekeypad lockout type UP

| Keypad Lockout <br> Lock Password | Util |
| :--- | :--- |

Off, Lock Password or Lock Cycle Tests Password

Press the RIGHT arrow to selectlockout value

Right

| Keypad Lockout | Util |
| ---: | ---: |
| $\underline{0} 00000$ |  |

Press the UP or DOWN arrow to changelockout value
UP
$\left.\begin{array}{|rr|}\hline \text { Keypad Lockout } & \text { Util } \\ 888888\end{array}\right]$

0 through 9 for all six digits
Use Right Arrow to select
(move to) next digit

## Condensed Operating Instructions

## RS-232 Baud Rate

Press the RIGHT arrow to select RS-232 baud rate

Right $\quad$| RS232 Baud Rate Util |
| :--- |
| 9600 |

Press the UP or DOWN arrow to change RS-232 baud rate value

UP $\boldsymbol{A} \quad$\begin{tabular}{l}
RS232 Baud Rate Util <br>
19200

$\quad$

9600, 19200, 9600Auto, <br>
19200Auto, or Disabled
\end{tabular}

## IEEE-488 Address

Press the RIGHT arrow to select IEEE-488 address

Right


Shown only if RS-232 Baud Rate is Disabled

Press the UP or DOWN arrow to change IEEE-488 address value

UP $\quad$| IEEE-488 Address Util |
| :--- |
| 16 |$\quad 1$ through 16

## Clear All Tests

Press the RIGHT arrow to select clear all tests

Right
Clear All Tests Util
No

Press the UP or DOWN arrow to change clear all tests

UP $\quad$| Clear All Tests Util |
| :--- |
| Yes |$\quad$ No or Yes

NOTE: If YES is selected, press Right arrow, Up arrow and Right arrow again to clear all tests.

## Condensed Operating Instructions

## Leveling

Press the RIGHT arrow to select leveling


Press the UP or DOWN arrow to change leveling value


## Cable Compensation

Press the RIGHT arrow to select cable compensation Right

Cable Comp. Util
Front Panel Connect

Press the UP or DOWN arrow to change cable compensation type
UP

| Cable Comp. <br> 1M Cable | Util |
| :--- | :--- |

1M, 2M or No Cable

## Frequency Edit Type

Press the RIGHT arrow to select frequency edit type

Right
Freq. Edit Type Util Discrete

Press the UP or DOWN arrow to change frequency edit type

UP $\quad$\begin{tabular}{lll}

\hline | Freq. Edit Type Util |
| :--- |
| Continuous | \& | Continuous or Discrete |
| :--- |
| Refer to paragraph 2.5.12 | <br>

\hline
\end{tabular}

## Condensed Operating Instructions

## Median

Press the RIGHT arrow to select median


Press the UP or DOWN arrow to change median type

UP $\quad$\begin{tabular}{lll}

\hline | Median |
| :--- |
| Median of 3 |$\quad$ Util $\quad$| Single Measurement or |
| :--- |
| Median of 3 measurements | <br>

\hline
\end{tabular}

## Distortion

Press the RIGHT arrow to select distortion


Press the UP or DOWN arrow to change distortion type


## Serial Number

Press the RIGHT arrow to display instrument serial number Right

```
Serial Number
0126789
```


## Software Version

Press the RIGHT arrow to display instrument software version

Right
Software Version Util V1.32

Press [UTILITY] to exit Utility Mode and return to Ready Mode

## Condensed Operating Instructions

## Connection to Device Under Test (DUT)

Figure COI-1 illustrates the connection of the 1920 LCR Meter to a device under test using the 4-BNC to 2-Kelvin Clip lead set (QT P/N 1700-03).


Figure COI-1: Connection to DUT using 1700-03 Kelvin Leads

| Connection to the Device under Test (QuadTech Cables) |  |  |  |
| :--- | :--- | :--- | :--- |
| Connection as labeled <br> on 1920 front panel | Connections with <br> cables labeled | Connections with <br> cables color coded | Connections with <br> cables color coded |
| PH connects to | PH or HS | red/white | red |
| IH connects to | IH or HD | red | red |
| PL connects to | PL or LS | black/white | black |
| IL connects to | IL or LD | black | black |

## Initiating Measurements

1) The instrument must be in the READY mode, or displaying the results from a previous measurement before initiating a test

$$
\begin{array}{lll}
1 \mathrm{Ls} & \mathrm{Rs} & 1.0000 \mathrm{KHz} \\
1.000 \mathrm{~V} & \text { NoBias Auto High }
\end{array}
$$

2) Test conditions and Utility functions should be programmed as previously described in this section.

## OR

Select the test number by pressing the Up or Down arrow key, if known test conditions are already stored in internal memory.

6 Prim Param Ready Automatic

## Condensed Operating Instructions

3) Make sure the device under test (DUT) is connected to the instrument as previously described.
4) To initiate a test on the device press the START key.
5) The LCD display shows the measured results depending on the operator programming of Display Type and Numeric Format. Typical display is shown below.

| $\begin{array}{ll} 1 & \text { Ls } \\ \text { Bin } 1 & Q \end{array}$ | $\begin{gathered} 158.460 \mu \mathrm{H} \\ 2.4890 \end{gathered}$ | $\begin{array}{lll} 1 \mathrm{dev} & \text { Ls } & 8.460 \mu \mathrm{H} \\ \operatorname{Bin} 1 & \mathrm{Q} & 0.4890 \end{array}$ |
| :---: | :---: | :---: |
| Measured Parameters |  | Deviation from Nominal |
| 1 \%dev Ls <br> Bin $1 \mathrm{C} Q$ | $\begin{array}{r} 5.46 \% \\ 22.25 \% \end{array}$ |  |

\% Deviation from Nominal, Binning On, Load Correction On

Other variations of measurement results


If binning is enabled the Pass or Fail indicator will be lit at the completion of test. Even if binning is not enabled the Pass indicator will still light at the end of the test indicating the test has been completed.

## Section 1: Introduction

### 1.1 Unpacking/Inspection

Inspect the shipping carton before opening. If damaged contact the carrier agent immediately. Inspect the 1920 Precision LCR Meter instrument for any damage. If the instrument appears damaged or fails to meet specifications notify QuadTech (refer to instruction manual front cover) or its local representative. Retain the shipping carton and packing material for future use such as returning for re-calibration or service.

### 1.2 Product Overview

The 1920 Precision LCR Meter is designed to perform impedance measurements on a wide variety of electronic components and materials. The 1920 covers a frequency range from 20 Hz to 1.0 MHz with a basic accuracy of $0.1 \%$. The user can select measurement and display two impedance or voltage parameters simultaneously and select engineering or numeric display of test results as well as deviation or \% deviation from a programmed nominal value. The 1920's AC test signal is programmable from 20 mV to 1 V and DC bias voltage programmable from 0 to 2 V .

The 1920 Precision LCR Meter also provides the capability to run up to six different tests in sequence, each with uniquely programmed test conditions and displayed parameters. For pass/fail testing or sorting of parts, the instrument provides 14 programmable bins. For fast component handling or automated system applications the 1920 comes standard with a handler I/O port, RS-232 and IEEE-488 interfaces.

For measurement integrity the 1920 includes four-terminal Kelvin connections and a load correction feature, whereby a measurement is performed on a known standard and a correction applied to subsequent measurements.

### 1.3 Front Panel Description

Figure 1-1 illustrates the controls and indicators on the front panel of the 1920 Precision LCR Meter. Table 1-1 identifies them with description and function.


Figure 1-1
Front Panel Controls and Indicators

Table 1-1
Front Panel Controls and Indicators

| Reference <br> Number <br> Figure 1-1 | Name | Type | Function |
| :--- | :--- | :--- | :--- |
| 1 | POWER | Rocker Switch | Applies AC power to unit: 1 (ON) 0 (OFF) |
| 2 | START | Push Button | Starts a measurement |
| 3 | STOP | Push Button | Stops any measurement in process |
| 4 | Left/Right arrows | In READY mode moves to the next or previous test <br> parameter for viewing <br> In PROGRAM or UTILITY mode moves to the next <br> or previous parameter for programming |  |
| 5 | PROGRAM | Push Button | In READY mode moves to the next or previous test <br> for viewing <br> In PROGRAM or UTILITY mode changes the <br> condition of the selected parameter |
| 6 | UTILITY. | Push Button | To enter and exit the PROGRAM mode (for changing <br> test conditions) |
| 7 |  | To enter or exit the UTILITY mode (for functional <br> changes which affect all tests) |  |

Table 1-1 (continued)

## Front Panel Controls and Indicators

| 8 | IH | BNC female connector | Current high connection to DUT |
| :--- | :--- | :--- | :--- |
| 9 | PH | BNC female connector | Potential high connection to DUT |
| 10 | PL | BNC female connector | Potential low connection to DUT |
| 11 | IL | BNC female connector | Current low connection to DUT |
| 12 | LOCKOUT | Green LED Indicator | Indicates front panel keypad lockout is enabled |
| 13 | REMOTE | Green LED Indicator | Indicates instrument has been enabled for remote <br> operation |
| 14 | BIAS ON | Green LED Indicator | Indicates internal DC bias voltage is applied |
| 15 | FAIL | Red LED Indicator | Indicates programmed test conditions and instrument <br> function or measured test results |
| 16 | PASS | Indicates measured results failed based on <br> programmed limits |  |
| 17 | Green LED Indicator | Indicates measured results passed based on <br> programmed limits, or test is complete if no limits are <br> programmed |  |

### 1.4 Rear Panel Description



Figure 1-2
Rear Panel View

Table 1-2
1920 Rear Panel Controls and Indicators

| Reference <br> Number <br> Figure 1-2 | Name | Type | Function |
| :--- | :--- | :--- | :--- |
| 1 | AC Inlet Module | 3-prong receptacle and fuse <br> draw | Fuse draw and 3-wire connection for AC power <br> Source. 2.5A, 250V fuse for 100-240 volt operation |
| 2 | RS-232 | 9 pin DB-Type connector | Input/Output connections for RS-232 interface |
| 3 | Remote I/O | 37 pin DB-Type connector | Input/Output connections for handler interface |
| 4 | IEEE-488 | 24 pin connector | Input/Output connections for IEEE-488 interface |

## Note

User cable specifications for use with CE Mark 1920

| RS-232 | Shielded cable required |
| :--- | :--- |
| Remote I/O | Cable must be double shielded (inner braid and outer foil) |
| IEEE-488 | Shielded cable required |

### 1.5 Installation

### 1.5.1 Dimensions

The 1920 Precision LCR Meter is supplied in a bench configuration, i.e. in a cabinet with resilient feet for placement on a table or bench. Figure 1.3 illustrates the 1920 instrument dimensions. The unit can be configured for rack mount applications using the 2000-16 optional Rack Mount Flanges.


Figure 1-3
Instrument Dimensions

### 1.5.2 Instrument Positioning

The front panel includes a high resolution back lit LCD display. A front bail is provided so that the unit can be tilted back for convenient operator viewing. The optimum angle for viewing is straight onto the display. This means that for bench or rack operation the instrument should be positioned at eye level.

### 1.5.3 Power Requirements

$\triangle$
The 1920 can be operated from a power source between 100 and 240 Vac at a power line frequency of 50 to 60 Hz , no line voltage switching is necessary. Power connection to the rear panel is through an AC inlet module comprised of an AC connector and fuse drawer. Before connecting the 3-wire power cord between the unit and AC power the fuses should be in accordance with the power source, T2.5A, $250 \mathrm{~V}, 5 \times 20 \mathrm{~mm}$ (QuadTech PN 520049) for 115 or 220 V source. Always use an outlet which has a properly connected protection ground. The instrument is factory shipped with the 2.5A fuse in place. The instrument can be damaged if the wrong fuse is installed.

## WARNING <br> MAKE SURE THE UNIT HAS BEEN DISCONNECTED FROM ITS AC POWER SOURCE FOR AT LEAST FIVE MINUTES BEFORE PROCEEDING.



Figure 1-4
Fuse Drawer Location (\#1)

Remove the fuse drawer by inserting a small flat head screwdriver behind the small tab to force the draw outward. Refer to Figure 1-4.

Once the fuse drawer has been completely removed from the instrument remove the clear fuse tray from the drawer by lifting upward slightly on the long narrow black locking tab. This will allow the fuse tray to be removed from the fuse drawer. This tray contains the active fuse, left side (secured by holder) and spare fuse on the right side (if present). Refer to Figure 1-5.

Remove the active fuse from the holder by prying upward using a small flat head screwdriver. Insert the replacement fuse into the fuse holder.

Once the fuse has been installed in the holder and spare fuse (if desired) installed in the right side of the tray insert the tray back into the fuse drawer, push in and lock. The two silver contacts on the fuse tray should be positioned towards the outside.

Once the fuse tray has been installed in the drawer, reinstall the fuse drawer back into the instrument AC inlet module, push in and lock.


Figure 1-5
Fuse Dramer

### 1.5.4 Safety Inspection

$\triangle$Before operating the instrument, inspect the power inlet module or the rear panel to ensure that the properly rated fuse is in place, otherwise damage to the unit is possible. Refer to paragraph 1.5.3.

The instrument is shipped with a standard U.S. power cord, QuadTech P/N 4200-0300 (with Belden SPH-386 socket or equivalent, and 3-wire plug conforming to IEC 320). Make sure the instrument is only used with these cables (or other approved international cord set) which ensures that the instrument is provided with connection to protective earth ground.

The surrounding environment should be free from excessive dust to prevent contamination of electronic circuits. The surrounding environment should also be free from excessive vibration. The instrument should be positioned with consideration for ample air flow to the rear panel ventilation holes, an open space of at least 3 inches $(75 \mathrm{~mm})$ is recommended behind the rear panel. Do not expose the instrument to direct sunlight, extreme temperature or humidity variations, or corrosive chemicals.

When the 1920 is used in a rack installation (using the QuadTech 2000-16 Rack Mount Flanges) make sure the unit is secured using rack cabinet mounting rails, and not secured solely by these front panel flanges.

## Section 2: Operation/Programming

### 2.1 Terms and Conventions

Table 2-1 Measurement Unit Prefixes
Multiple
1000000000000000
1000000000000
1000000000
1000000
1000
.001
.000001
.000000001
.000000000001
.000000000000001

Frequency:

Ground:

Inductance:

Inductive Reactance:

Quality Factor:

| Scientific | Engineering | Symbol |
| :--- | :--- | :--- |
| $10^{15}$ | Peta |  |
| $10^{12}$ | Tera | P |
| $10^{9}$ | Giga | T |
| $10^{6}$ | Mega | G |
| $10^{3}$ | Kilo | M |
| $10^{-3}$ | milli | k |
| $10^{-6}$ | micro | m |
| $10^{-9}$ | nano | u |
| $10^{-12}$ | pico | n |
| $10^{-15}$ | femto | p |
|  |  | f |

The rate at which current or voltage reverses polarity and then back again completing a Full cycle, measured in Hertz (Hz) or cycles/second. AC Line Frequency $=50 / 60 \mathrm{~Hz}$.

The base reference from which voltages are measured, nominally the same potential as the earth. Also the side of a circuit that is at the same potential as the base reference.

Inductance is the property of a coil to oppose any change In current through it. The inductance of a coil varies as the number of turns squared $\left(\mathrm{N}^{2}\right)$. If the turns are stretched out, the field intensity will be less and the inductance will be less. The larger the radius or diameter of the coil, the longer the wire used and the greater the inductance.

A measure of how much the counter electro-magnetic force (EMF) of the coil will oppose current variations. The amount of reactance is directly proportional to the frequency of the current variation. $\mathrm{X}_{\mathrm{L}}=2 \pi \mathrm{fL}$

Quality factor is a measurement of the quality of an inductor: how tight the wire is wrapped (wound). The higher the Q the better the inductor. Q is equal to reactance divided by resistance. $\mathrm{Q}=\mathrm{X}_{\mathrm{S}} / \mathrm{R}_{\mathrm{S}}$

| Capacitance: | The ratio of charge on either plate of a capacitor to the Potential difference (voltage) across the plates. When a voltage is applied, current flows immediately at a high rate then exponentially decays toward zero as the charge builds up. If an AC voltage is applied, an AC current appears to flow continuously because the polarity of the voltage is reversed at the frequency of the applied voltage. The waveform of this current however is displaced in time from the applied voltage by $90^{\circ}$. |
| :---: | :---: |
| Capacitive Reactance: | A measurement of the actual AC resistance of a capacitor. How effective a capacitor may be in allowing AC to flow depends upon its capacitance and the frequency used. $\mathrm{X}_{\mathrm{C}}=1 / 2 \pi \mathrm{fC} .$ |
| Dissipation Factor: | Dissipation factor is a measurement of the quality of a capacitor: how well it dissipates charge. The lower the $\mathrm{D}_{\mathrm{f}}$, the better the capacitor. Dissipation factor is equal to resistance divided by reactance. $\mathrm{D}_{\mathrm{f}}=\mathrm{R}_{\mathrm{S}} / \mathrm{X}_{\mathrm{S}}=1 / \mathrm{Q}=$ $\tan \left(90^{\circ}-\theta\right)=\tan \delta$. |
| Impedance: | In AC circuits, impedance is the "AC resistance" to the flow of current through a circuit when an AC voltage is applied across the terminals of that circuit. Impedance is composed of real (in phase with voltage) and reactive (out of phase by $90^{\circ}$ ) components. $\mathrm{Z}=\mathrm{E} / \mathrm{I}=\mathrm{R}+\mathrm{jX}$ Impedance $=$ resistance + reactance . |
| Series Circuit: | Designated with a subscript $S$ in equations and Figure 2-2. |
| Parallel Circuit: | Designated with a subscript P in equations and Figure 2-2. |
| Nominal Value: | Value inputted by operator. The display will show deviation or \% deviation of the DUT from the Nominal Value. |
| Dielectric Absorption: | The physical phenomenon in which insulation appears to Absorb and retain an electrical charge slowly over time. Apply a voltage to a capacitor for an extended period of time, then quickly discharge it to zero voltage. Leave the capacitor open circuited for a period of time then connect a voltmeter to it and measure the residual voltage. The residual voltage is caused by the dielectric absorption of the capacitor. |

## $2.2 \quad$ Power Up

Once the 1920 is powered up it is ready for immediate testing if test conditions have been previously stored in one of the internal memory locations (user tests 1 thru 30). Any of these test conditions and other instrument settings can be changed by easy-to-use menu functions. For use of the functions refer to the Condensed Operating Instructions in the front of this manual and for more detailed descriptions and uses of these functions refer to Program/Setup procedure which follows.
Connect the power cord (female end) to the AC inlet module on the rear panel of the instrument. Connect the other end (male end) to the power receptacle. The instrument is to be used only with three wire grounded outlets, 115 or 230 V , no line voltage switching is required.

WARNING
DO NOT TURN INSTRUMENT POWER ON OR OFF WITH TEST DEVICES CONNECTED.

Power is applied to the 1920 by pressing the front panel POWER switch to ON (1 position). The instrument sequences through a initialization routine, display of operating software version, and to the Ready mode of the test setup \# in which a measurement was made before the unit was last powered down.


### 2.3 Program/Setup Procedure (Test 1-30)



Figure 2-1: Typical Display

The above display is typical on power-up, with the programmed test conditions shown for setup \# 1, in the Ready state.

## To view programmed setups

To select any test setup number for viewing simply press the Up or Down arrow keys while in the Ready state (user test 1-30, or sequence S1-S9) and press Right arrow key to view individual test parameters. Sequence tests (S1-S9) can be any combination of user tests (up to a maximum of 6), these are discussed in paragraph 2.4.

## To program setups

Select the desired test setup number by pressing the Up or Down arrow keys while in the Ready state shown above, then press the PROGRAM key to enter the program mode.

Program mode can be exited at any time and instrument returned to Ready state by pressing PROGRAM key or program mode is exited automatically after sequencing through all test parameters with Right arrow key.

Programmable functions are discussed below.


### 2.3.1 Primary Parameter

Any combination of two AC parameters, or two DC parameters, can be measured and displayed simultaneously on the 1920, one referred to as the Primary (displayed first) and the other the Secondary (see paragraph 2.3.2). The instrument can be set for a primary parameter selection of Auto, a feature which enables any passive component to be measured without knowing what type of component it is. The parameter selection can be chosen by the operator through menu selection as shown below.


| 1Prim Param <br> Automatic | Program |
| :--- | :--- |


| 1 Prim Param |
| :--- | :--- |
| Ls |

Ls thru DCI
Right arrow key to program
next parameter
or

| 1Prim Param Program <br> DCI |
| :--- |

PROGRAM key to exit Program Mode and return to Ready mode.

The following selections are possible and discussed in more detail below.

Ls - Inductance in henries
Lp - Inductance in henries
Rs - Resistance in ohms
Rp - Resistance in ohms
Cs - Capacitance in farads
Cp - Capacitance in farads
DF- Dissipation Factor (no units)
Q - Quality Factor (no units)
|Z| - Impedance in ohms
$|\mathrm{Y}|$ - Admittance in siemens

P - Phase Angle in degrees
|ESR|-Equivalent series resistance in ohms
Gp - Conductance in siemens
Xs - Reactance in ohms
Bp - Susceptance in siemens
V - AC voltage across the DUT
I - AC current thru the DUT
DCV - DC voltage across the DUT
DCR - DC resistance in ohms
DCI - DC current thru the DUT

$$
\begin{aligned}
& s=\text { series equivalent circuit } \\
& p=\text { parallel equivalent circuit }
\end{aligned}
$$

An impedance that is neither a pure resistance nor a pure reactance can be represented at any specific frequency by either a series or a parallel combination (s or p) of resistance and reactance. Such a representation is called an equivalent circuit. The value of the primary measurement of a device depends on which equivalent circuit, series or parallel, is chosen to represent it. The manufacturer or user of a device specifies how a device is to be measured (usually series) and at what frequency. If this is not known, be sure to specify if the results were series or parallel and what the measurement frequency was. Series and parallel equivalent circuits for a lossy inductor and lossy capacitor are shown in Figure 2-2.


Figure 2-2
Series and Parallel Circuits for both Capacitive and Inductive Impedances

Impedance is the parameter used to characterize electronic components, materials and circuits. Impedance $|Z|$ is defined as the opposition a device or circuit offers to the flow of ac current at a particular frequency and generally represented as a complex quantity consisting of a real part (resistance, R) and imaginary part (reactance, jX ). Impedance can be expressed using the rectangular coordinate form ( $\mathrm{R}+\mathrm{jX}$ ) or polar form as magnitude and phase angle $(|\mathrm{Z}| \angle \theta)$. Figure 2-3a shows the mathematical relationship between $R, X,|Z|$, and $\theta$ for both inductive and capacitive devices. In some cases it becomes mathematically practical to represent impedance using the reciprocal where $1 /|\mathrm{Z}|$ $=|\mathrm{Y}|=\mathrm{G}+\mathrm{jB}$, where $|\mathrm{Y}|$ represents admittance, $G$ conductance, and $B$ susceptance. This mathematical relationship is shown in Figure 2-3b for inductive and capacitive devices.


Figure 2-3a

## Phase Diagrams of Impedances



Figure 2-3b
Phase Diagrams of Admittances

Quality factor $(\mathrm{Q})$ is used as a measure of a reactance's purity (how close it is to being a pure reactance, i.e. no resistance) and defined as the ratio of the energy stored in a device to the energy dissipated by the device. Q is dimensionless and is expressed as $\mathrm{Q}=\mathrm{X} / \mathrm{R}=$ $\mathrm{B} / \mathrm{G}$. From Figure 2-3 one can see that Q is the tangent of the angle $\theta$. Q is commonly applied to inductors and for capacitors the term generally used to express purity is Dissipation Factor (D), which is the reciprocal of Q.

### 2.3.2 Secondary Parameter

(not shown if Primary Parameter selected for Automatic)

As in the primary parameter selection the secondary parameter can be chosen by the operator for display. When the primary parameter is selected for Automatic the secondary is determined by it. For example, if the primary display is selected for capacitance (C) the secondary defaults to dissipation factor (D) or for a primary of inductance (L) the secondary defaults to quality factor (Q). The following secondary parameters may be chosen:

No Secondary Param, Ls, Lp, Rs, Rp, Cs, Cp, DF, Q, Z, Y, P, ESR, Gp, Xs, Bp, V, I


Right arrow key to program
next parameter
or
PROGRAM key to exit Program
Mode and return to Ready mode.

### 2.3.3 Frequency

(not shown if Primary Parameter selected for DCV, DCR or DCI)

This function allows the user to program the frequency of the AC test signal between 20 Hz and 1 MHz using two different methods. When the Utility function Freq. Edit Type is selected for Discrete, selection is made from 15 possible frequencies selections over this range, or when Freq. Edit Type is selected for Continuous, the frequency can be selected in increments of 1 Hz below 100 kHz and increments of 10 Hz above 100 kHz . Refer to Utility functions, paragraph 2.5 for information on the frequency edit type.

When discrete is selected the 16 possible frequencies are:
$20,50,100,200,400,500 \mathrm{~Hz}, 1,2,5,10,20,50,100,200,500 \mathrm{kHz}$, and 1 MHz


Right - arrow key to program next parameter
or
PROGRAM key to exit Program Mode and return to Ready mode.

### 2.3.4 Amplitude

This function allows the user to program the AC test voltage amplitude between 20 mV and 1.0000 V in 5 mV steps. The programmed voltage is maintained at the instrument terminals with the terminals open, but not necessarily at the DUT. The actual voltage across the DUT is never more than the programmed voltage, and depends on the DUT impedance and source resistance of the 1920 , which can be $5 \Omega, 25 \Omega 50 \Omega$ or $100 \Omega$. Refer to Utility functions, paragraph 2.5 .6 for information on the source impedance. The instrument source resistance must be taken into consideration especially when measuring low values of impedance (low inductance or high capacitance).

For example, if the programmed amplitude voltage is 1 V , the source resistance set for $50 \Omega$, and the impedance of the unknown DUT $50 \Omega$, the voltage across the DUT is not 1 V but rather 0.5 V .


Right $>$ arrow key to program
next parameter
or
PROGRAM key to exit Program
Mode and return to Ready mode．

## 2．3．5 Bias Voltage

ニーー This function allows the user to program DC bias voltage to Off，from 1mV to $\mathbf{2 V}$ in 1 mV steps，or AC Coupled．When selected for Off no bias voltage is applied to the device under test，when programmed for a bias voltage this DC voltage is applied to the device under test．When selected for AC Coupled a large value blocking capacitor is switched in to protect the 1920 measurement circuit from DC voltages．This mode of operation is intended primarily for battery impedance measurement applications．

The BIAS ON indicator，serves to indicate if internal bias voltage has been programmed for a value．

When DC bias is to be applied to a device observe the correct polarity when connecting the bridge or inserting the device in a test fixture．Bias POSITIVE polarity is applied to the high terminals（ $\mathbf{P H}, \mathbf{I H}$ ），and bias NEGATIVE polarity applied to the low terminals（PL，IL）．It is good practice to wait approximately 1 second after initiating a measurement before taking a reading，this allows the device to stabilize after bias is applied．When the instrument is triggered remotely，a programmed delay is advisable to ensure that the device has stabilized．

When applying a bias voltage there are effects to be aware of in watching for stabilization of the DUT：voltage and capacitance．Besides charging to a final voltage，there is also the stabilization of capacitance value itself．For example，some electrolytic capacitors respond slowly to a change in applied voltage，therefore the capacitance can be changing well after the voltage is stable．In general DC bias should only be applied to capacitors， unreliable measurement results can occur if DC bias is applied to low impedance devices．

| 1 | Bias Voltage Program |
| :--- | :--- |
| Off |  |



Right arrow key to program
next parameter
or
PROGRAM key to exit Program
Mode and return to Ready mode.

### 2.3.6 Range Select

This function allows the user to manually select a measurement range. There are 27 current/voltage range combinations ( 45 for DC ), but the test frequency will determine which ranges are selectable. To eliminate operator errors in range setting and ensure specified instrument accuracy it is generally best to set the range for Auto. When Auto is selected the instrument automatically selects the optimum range for the impedance being measured at the selected test voltage and frequency.

Range Hold, when selected, will hold the optimum measurement range for the test conditions programmed and the device being measured. The unit determines the selection on the first measurement by measuring the device in Auto range mode and then holding it.
Range Lock, allows the operator to select one of the fixed ranges as listed below.
In either case, it is important to note that when a range is held or locked which is not the range that instrument's auto ranging would of selected (for DUT impedance and programmed test conditions) some accuracy may be sacrificed or the instrument may be unable to complete a test of a particular DUT.

## Up or Down to change range <br> arrow key

| 1Range Select <br> Auto | Program |
| :--- | :--- |


| Range Select <br> Hold |  |
| :--- | :--- |


| 1 Range Select Program Lock 200 mA , any F 1.0V |  |
| :---: | :---: |
|  |  |
| 27 ranges (45 for DC) |  |
|  |  |
| 1 Range Select Program Lock 2.6 $\mathrm{HA} \quad \mathrm{F}<=10 \mathrm{~K} 62 \mathrm{mV}$ |  |
|  |  |

Right arrow key to program
next parameter
or
PROGRAM key to exit Program Mode and return to Ready mode.

Table 2-2
Manual Range Selection

|  | AC Impedance Measurements |  | DCR \& DCV Measurements |
| :--- | :---: | :--- | :--- |
| Maximum Measurable <br> Voltage Across DUT | Maximum Measurable AC <br> Current to DUT | User Programmed <br> Test Frequency | Maximum Measurable DC <br> Current to DUT |
|  | 200 mA | 20 Hz to 1 MHz | 200 mA |
|  | 40 mA | 20 Hz to 1 MHz | 40 mA |
|  | 10 mA | 20 Hz to 1 MHz | 10 mA |
|  | 2.67 mA | 20 Hz to 1 MHz | 2.67 mA |
|  | $668 \mu \mathrm{~A}$ | 20 Hz to 1 MHz | $668 \mu \mathrm{~A}$ |
|  | $167 \mu \mathrm{~A}$ | 20 Hz to $\leq 250 \mathrm{kHz}$ | $167 \mu \mathrm{~A}$ |
|  | $42 \mu \mathrm{~A}$ | 20 Hz to $\leq 250 \mathrm{kHz}$ | $42 \mu \mathrm{~A}$ |
|  | $11 \mu \mathrm{~A}$ | 20 Hz to $\leq 10 \mathrm{kHz}$ | $11 \mu \mathrm{~A}$ |
|  | $2.6 \mu \mathrm{~A}$ | 20 Hz to $\leq 10 \mathrm{kHz}$ | $2.6 \mu \mathrm{~A}$ |
| 250 mV | 9 ranges as listed above | 9 ranges as listed <br> above | 9 ranges as listed above |
| 62 mV | 9 ranges as listed above | 9 ranges as listed <br> above | 9 ranges as listed above |
| 22 mV |  |  | 9 ranges as listed above |
| 6 mV |  |  | 9 ranges as listed above |

## NOTE

The best way to determine the optimum range for a test device at programmed conditions is to change the primary parameter selection to V (AC voltage across the device), secondary parameter to I (current through the device), and initiate a test. The voltage and current measured can be compared to the previous table where the appropriate range is determined with the measured values falling below the maximums listed.


Note: 200 mA range must use $5 \Omega$ source impedance (see paragraph 2.5.6)

### 2.3.7 Accuracy

This function allows the user to program four possible setting for measurement accuracy, Low, Medium, High or Low (No Display). Note, that when programmed for Low No Display, measurement data is not available via IEEE-488 or RS-232 interfaces, but only available as binning data through the Remote I/O interface. The instrument will make a more precise measurement when programmed for High, but there is a tradeoff in measurement speed as indicated below.

Table 2-3: 1920 Accuracy

| Accuracy Setting | Measure Time | Measure Speed | Nominal Accuracy |
| :---: | :---: | :---: | :---: |
| Low | 40 ms | $25 \mathrm{meas} / \mathrm{sec}$ | $0.5 \%$ |
| Medium | 100 ms | $10 \mathrm{meas} / \mathrm{sec}$ | $0.25 \%$ |
| High | 1 s | $1 \mathrm{meas} / \mathrm{sec}$ | $0.1 \%$ |
| Low (No Display) | 25 ms | $40 \mathrm{meas} / \mathrm{sec}$ | $0.5 \%$ |

NOTE
Measurement times may be longer depending on frequency and other test conditions. One complete cycle of
stimulus voltage is required for measurement.

| 1 | Accuracy Program |
| :--- | :--- |
| Low ( 40 ms test) |  |


| 1 | Accuracy Program |
| :--- | :--- |
| Medium (100 ms test) |  |


| 1 | Accuracy Program |
| :--- | :--- |
| High (1 second test) |  |


| 1 | Accuracy | Program |
| :--- | :--- | :--- |
| Low, No Display | (25ms) |  |

Right arrow key to program
next parameter
or
PROGRAM key to exit Program
Mode and return to Ready mode.

## The 1920 has three basic levels of accuracy

## Basic For AC

High 0.10\%
Medium 0.25\%
Low \& Low No Display 0.5\%
The actual accuracy at a given test condition is defined by the following formula:

$\mathrm{V}=$ Programmed test voltage $\left(\mathrm{V}_{\text {SOURCE }}\right)$
Freq = Programmed test frequency
$|Z|=$ DUT impedance

## NOTE

For frequencies above $100 \mathrm{kHz} \mathrm{V}_{\text {DUT }}$ must be at least 20 mV . That is $V_{\text {DUT }}=V_{\text {SOURCE }}\left(\frac{Z_{\text {DUT }}}{Z_{\text {DUT }}+R_{\text {SOURCE }}}\right)$
$\mathrm{Z}_{\text {Max }}$ is $4 * 10^{5}$ for Frequency less than 10 kHz
$2.5 * 10^{4}$ for Frequency less than 250 kHz
$1.5 * 10^{3}$ for Frequency above 250 kHz

$$
\begin{aligned}
& D F_{\text {ACCURACY }}=\left[\frac{\text { Accuracy \% }}{100}+\frac{D F}{50}\right]\left[1+\sqrt{\frac{\text { Freq }}{50000}}\right] \\
& Q_{\text {ACCURACY }}=\left[\frac{\text { Accuracy \% }}{100}\right]+\left[|Q|\left[0.02+\frac{\text { Accuracy \% }}{100}\right]\right]+\left[Q^{2}\left[\frac{\text { Accuracy \% }}{200}\right]\right]
\end{aligned}
$$

## Basic For DC

High 0.20\%
Medium 0.25\%
Low \& Low No Display 0.5\%
Accuracy $=\operatorname{Acc}_{\text {Basic }} \sqrt[\frac{3}{2}]{\frac{1}{V}}\left(1+\frac{0.3}{R}+\frac{\mathrm{R}}{\mathrm{R}_{\text {Max }}}\right)$
$\mathrm{R}=\mathrm{DC}$ Resistance
$\mathrm{R}_{\text {Max }}=400 \mathrm{k} \Omega$

## For Capacitors If DF > . 1

$$
\text { Accuracy:= Accuracy } \sqrt{1+\mathrm{DF}^{2}}
$$

For Inductors if Q < 10

$$
\text { Accuracy:= Accuracy } \sqrt{1+\left(\frac{1}{\mathrm{Q}}\right)^{2}}
$$

Note: Due to the large time constants involved in measurements of high value inductors, additional inaccuracies may result. This will be indicated by reduced display resolution.

Temperature: Error doubles for every $10^{\circ} \mathrm{C}$ from $23^{\circ} \mathrm{C}$

### 2.3.8 Delay

This function allows the user to program a delay time between $\mathbf{0}$ and $\mathbf{1 0 0 s}$ in 10 ms steps. This is a programmable delay time from the internal or external trigger command to the start of the measurement. In many cases it is helpful to have a time delay before actually making measurements. Such a delay allows time for switching transients or mechanical handling to settle.

Up or Down $\boldsymbol{\nabla}$ arrow key to change delay time


Right arrow key to program next parameter
or
PROGRAM key to exit Program
Mode and return to Ready mode.

### 2.3.9 No. to Average

This function allows the user to program the number of measurements to average between 1 and 999. If the entered value is 1 , averaging is disabled and the display is updated with each individual measurement. If the entered average is 10 the instrument will make 10 measurements and then display the average value. When the instrument is in a continuous measurement mode the display is retained until the next average of 10 is complete. Averaging improves the measurement accuracy over the single measurement accuracy by $\frac{1}{\sqrt{n}}$, but never less than $0.1 \%$ for the parameter and $0.1 \%$ or 0.001 for the secondary. $\mathrm{n}=$ no. to average.


Right arrow key to program next parameter
or
PROGRAM key to exit Program Mode and return to Ready mode.

### 2.3.10 Primary Nominal

The Primary Nominal value (programmable by the operator) can serve as a basis for three functions:

1) The nominal value for the primary binning functions. Refer to paragraph 2.3.11.
2) The nominal value for calculating Deviation or \% Deviation when the measurement results are programmed to be display in this format. Refer to paragraph 2.5.3.
3) The nominal value (or actual known value) when implementing the load correction feature of the 1920. Refer to paragraph 2.3.13.

This function allows the user to select a nominal value for the primary displayed parameter, selection of nominal value for the secondary parameter is discussed in paragraph 2.3.12. One technique for determining the approximate nominal values (or starting point) is to first measure the DUT and then fine tune as indicated below. The units for the nominal value ( $\Omega, \mathrm{mH}, \mu \mathrm{F}$, etc.) are determined by operator selection of the Primary Parameter.


Right arrow key to program next parameter
or
PROGRAM key to exit Program
Mode and return to Ready mode.

### 2.3.11 Bin Type

A group of similar components can be measured and categorized according to operator programmed limits. For example, the 1920 can be used to sort a group of nominallyvalued $100 \mathrm{k} \Omega$ resistors into assigned bins of $1 \%, 2 \%, 5 \%$, etc., around a nominal value, or sorted by absolute limits which are independent of any nominal value. The 1920 provides sorting capability into 14 bins (10 pass and 4 fail). These are assigned as follows:

| Bins 1 thru 10 | Primary pass, secondary pass (if limit is entered) |
| :--- | :--- |
| Bin 11 | Primary pass, secondary fail low |
| Bin 12 | Primary pass, secondary fail high |
| Bin 13 | Primary fail, secondary pass |
| Bin 14 | Primary fail, secondary fail |

If no limit is entered for the primary parameter but one is entered for the secondary, bin assignment will be Bin 1 for a pass and Bin 11 for a fail low and Bin 12 for a fail high.

Bin limits for the primary parameter can be entered in terms of absolute value or as a percent tolerance about a defined nominal. Two of the most common methods of sorting are nested limits and sequential limits. Nested limits are a natural choice for sorting by \% tolerance around a single nominal value with the lower numbered bins narrower than the higher numbered ones. Nested limits for five bins are illustrated below, note that limits do not have to be symmetrical as shown for bin 5 , which is $+20 \%$ and $-30 \%$. When entering limits in percent, both can be positive, both can be negative, or one can be positive and one can be negative, but the Hi limit must be more positive than the Lo limit.


Sequential limits are a natural choice for sorting by absolute value. Sequential limits for four bins are illustrated below. It should be noted that the bins do not necessarily have to be adjacent. Depending on the specified limits for each they can be overlapping, adjacent or even isolated (gaps) from each other. Any overlap is assigned to the lower numbered bin and a gap would be assigned to the overall fail bin.

$\underset{\text { Up or Down }}{\text { to change bin type }} \underset{\underset{\sim}{\boldsymbol{T}}}{\text { arrow key }}$


| 1 | Bin Type |
| :--- | :--- |
| Pct. Deviation |  |

## Note:

To set a Hi and Lo limit to Off,
Up or Down arrow to change one of the limits to the value entered for its counterpart. For example: If the Absolute HiLim is $110 \Omega$ and LoLim is $90 \Omega$ (or \% deviation limits are $+10 \%$ and $-10 \%$ )
Down $\boldsymbol{\nabla}$ arrow the HiLim to $90 \Omega$ (or $-10 \%$ ) to select Off

Right arrow key to select bin 1 limits in \%

| 1 | Bin 1 HiLim Program |
| :--- | :--- |
| Off $\%$ |  | Up or Down $\boldsymbol{\nabla}$ arrow key to change bin 1 Hi \% limit



Right
arrow key to

$\wedge$
Up or Down $\boldsymbol{\nabla}$ arrow key to change bin 1 Lo \% limit


Right $>$ arrow key to program next parameter
or
PROGRAM key to exit Program Mode and return to Ready mode.


1 Bin Type
Program

Right arrow key to select bin 1 limits in absolute

| 1 Bin 1 HiLim | Program |
| :---: | :---: |
| 100.00 mH |  |

Up or Down $\boldsymbol{\nabla}$ arrow key to change bin 1 Hi absolute limit

| 1 Bin 1 HiLim | Program |
| :--- | :--- |
| 110.00 mH |  |

Right arrow key to select bin 1 Lo limit in absolute
1 Bin 1 LoLim
90.000 mH

| Up or Down $\boldsymbol{\nabla}$ arrow <br> key to change bin 1 <br> Lo absolute limit | 1 Bin 1 LoLim 80.000 mH | Program |
| :---: | :---: | :---: |

Right arrow key to select bin 2 thru 10 Hi and Lo limits and

Up Down $\boldsymbol{\nabla}$ to change these limits

PROGRAM key, at any time, to return to Ready mode


Bin 2 thru 10, Hi \& Lo limits

1 Bin 10 LoLim Program Off

### 2.3.12 Secondary Nominal

(not shown if Secondary Parameter is set to "No Secondary parameter")
This function allows the user to select a nominal value for the secondary displayed parameter and to program high and low limits around this nominal. These limits are selected in absolute value or \% deviation about this nominal (determined by bin type selection, refer to paragraph 2.3.11). The limits do not have to be symmetrical; there is an independent limit for both the high and low values. The units for the nominal value ( $\Omega, \mathrm{mH}, \mu \mathrm{F}$, or absolute value) are determined by operator selection of the Secondary Parameter.

## Up or Down $\underset{\boldsymbol{\nabla}}{\boldsymbol{\nabla}}$ arrow key to enter change value

| 1 Sec Nominal <br> 1.0000 | Program |
| :---: | :---: |
| 1Sec Nominal <br> 10.000 Program |  |

Right arrow key to select secondary limits


Right arrow key to select secondary parameter Lo limit

| 1 Sec LoLim | Program |
| :--- | :--- |
| 1.0000 |  |



Right arrow key to program next parameter
or
PROGRAM key to exit Program Mode and return to Ready mode.

### 2.3.13 Load Correction

Load correction allows the user to specify the value of the component under test (user supplied standard) and apply a correction to subsequent measurements of similar components under the same test conditions. This feature corrects for instrument nonlinearity and for fixture effects which can be dependent on the test frequency, test voltage level or impedance range.

Measurement accuracy is 0.25 x (normal accuracy) with Load Correction implemented and compared to user supplied standard and for the same measurement conditions (test voltage, test frequency, and 1920 measurement range).

This increased accuracy applies in a range of:
DUT's with impedance (Z) between $3 \Omega$ and $800 \mathrm{k} \Omega$, with programmed voltage from 100 mV to 1 V

Load correction can be set to Off or On. Off disables any load correction, On enables load correction with any currently stored values. Press START performs a measurement on a DUT to determine the load correction based on the primary and secondary nominal values previously entered. Refer to paragraph 2.3.10 and 2.3.12. After a correction measurement, load correction is turned on, and the values can be observed in Primary and Secondary Load Correction displays. Refer to paragraphs 2.3.14 and 2.3.15. With load correction turned $\underline{\text { On }}$ these corrections are applied to ongoing measurements and the final corrected value displayed.


Right arrow key to next parameter and observe load corrections
or
PROGRAM key to exit Program Mode and return to Ready mode.

Press START to determine load corrections from measurement of the DUT (based on primary and secondary nominal values)


### 2.3.14 Primary Load Correction

The value shown is the measured load correction for the primary parameter, which can be further altered by the operator as shown below.

Primary Load Correction $=$ Load Correction Measured minus the Primary Nominal value)
For example, if the load correction measured is 148.000 nH (para 2.3.13) and the primary nominal is 140.000 nH , the primary load correction shown here would be -8.0000 nH .

| Up or Down |
| :--- | :--- | :--- |
| to change load correction | | 1 Pri LoadCorr |
| :---: | :---: |
| -8.0000 nH |$\quad$ Program |  |
| :--- |

Right - arrow key to program
next parameter
or
PROGRAM key to exit Program
Mode and return to Ready mode.

### 2.3.15 Secondary Load Correction

The value shown is the measured load correction for the secondary parameter, which can be further altered by the operator as shown below.

Secondary Load Correction $=$ Load Correction Measured minus the Secondary Nominal value)

For example, if the load correction measured is a Q of 10.5670 (para 2.3.13) and the secondary nominal is 10.0000 , the secondary load correction shown here would be -0.5670 .


Right arrow key or
PROGRAM key to exit Program
Mode and return to Ready mode.

### 2.4 Program/Sequence (Test S1-S9)

Sequence tests (S1 through S9) are selected by pressing Up or Down arrow key when instrument status is in the Ready or power up mode.


The above display is typical showing $\mathbf{S 1}$ is the sequence test setup \#, the sequence programmed to perform user tests $\mathbf{1 , 3 , 5 , 7 , 9}$, and 10 in succession, and Ready the instrument status. To select any other sequence test number simply press the Up or Down arrow keys while in the Ready state.

## Programming Sequence Test

| S1 |  |  |  |  |  |  | Ready |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| 2 | 4 | 6 | 8 | 10 | 12 |  |  |

To enter programming mode Press PROGRAM

| S1:1 | Program |
| :--- | :--- |
| Test : 2 |  |

## Sequence 1, Test 1

Up or Down $\stackrel{\Delta}{\boldsymbol{\nabla}}$ arrow key to change test \# for test 1

| S1:1 | Program |
| :--- | :--- |
| Test : |  |

Tests 1 - 30, skip or none

## Sequence 1, Test 2

Right arrow key to select test \# 2 in the sequence

| S1:2 | Program |
| :--- | :--- |
| Test : 4 |  |


| Up or Down <br> S1:2 <br> arrow key <br> to change test $\#$ for test 2 | Test : 5 | Program |
| :--- | :--- | :--- |

Tests $1-30$, skip or none

## Sequence 1, Test 3

Right arrow key to select test \# 3 in the sequence

Up or Down $\boldsymbol{\nabla}$ arrow key to change test \# for test 3

| S1:3 | Program |
| :--- | :--- |
| Test : 7 |  |

Tests $1-30$, skip or none

## Sequence 1, Test 4

Right arrow key to select test \# 4 in the sequence

Up or Down $\underset{\boldsymbol{\Delta}}{\boldsymbol{\Delta}}$ arrow key to change test \# for test 4

| S1:4 | Program |
| :--- | :--- |
| Test : 8 |  |


| S1:4 | Program |
| :--- | :--- |
| Test: 9 |  |

Tests $1-30$, skip or none

## Sequence 1, Test 5

Right arrow key to select test \# 5 in the sequence

| S1:5 | Program |
| :--- | :--- | :--- |
| Test : 10 |  |

Up or Down $\boldsymbol{\nabla}$ arrow key
to change test \# for test 5

| S1:5 |  |
| :--- | :--- |
| Test : | 11 |

Tests $1-30$, skip or none

## Sequence 1, Test 6

Right arrow key to select test \# 6 in the sequence

| S1: 6 | Program |  |
| :--- | :--- | :--- |
| Test: | 12 |  |

Up or Down
to change test $\#$ for test 6

| S1:6 | Program |  |
| :--- | :--- | :--- |
| Test : | 13 |  |

Tests $1-30$, skip or none

PROGRAM key to exit Program
Mode and return to Ready mode.

## Binning Function During Sequence Tests

During a sequence test, each single step user test within the sequence ( 1 to 6 ) will be assigned to a bin according to the limits programmed for that single test, in other words, the bin assignment will be to bin 1 thru 14, the same as if the test was run as a single test. This is the bin assignment that will be shown when the results of a sequence is reviewed on the display or output remotely with a FETCH command. The bin assignment output through the Remote I/O output will be somewhat different. The bin outputs will not be asserted until all tests in a sequence have been completed, and the assignment will be bin 1 if all tests ( 1 to 6 ) pass or will be $(\mathrm{N}+1)$, where N is the number of the first test that fails. One of these 7 bin outputs will always be asserted during a sequence test, even if all binning is turned Off, bin 1 is asserted as a Pass.

### 2.5 Utility Functions

The Utility functions allow the user to set instrument functions that affect all tests. When the UTILITY key is pressed the first function, Cal, and other functions (as list below) are accessed by pressing the Right arrow ke BOLD settings are the default settings.

Table 2-3
Programmable Parameters For Utility Functions

| Programmable Functions | Settings |
| :---: | :---: |
| Cal with X M Cable | Cal Due: 1/ 1/2001 <br> Quick Short Cal <br> Quick Open Cal <br> Quick Short/Open Cal <br> Short Cal <br> Open Cal <br> Short/Open Cal <br> Full Cal |
| Keypad Lockout | Lock Password, Off Lock Cycle Tests Passwd |
| Display Type | Measured Parameters Dev. from Nominal \% Dev. from Nominal |
| Numeric Format | Engineering, Scientific |
| Trigger Source | Internal, External |
| Source Impedance | $5 \Omega, 25 \Omega, 50 \Omega, 100 \Omega$, |
| RS232 Baud Rate | 9600, 19200, 9600AutoReport 19200AutoReport, Disabled |
| IEEE-488 Address | 1 to 16 (factory default set for 3) |
| Clear All Tests | No, Yes |
| Leveling | Off, On |
| Cable Compensation | No Cable 1 M Cable <br> 2 M Cable |
| Freq. Edit Type | Discrete Continuous |
| Median | Single Meas. <br> Median of 3 |
| Distortion | Not tested Check during AC test |
| Serial Number | XXXXXXX |
| Software Version | VX.XX |

The Utility Function, factory shipped conditions, are as follows:

| Keypad Lockout: | Off | Clear All Tests: | No |
| :--- | :--- | :--- | :--- |
| Display Type: | Measured Parameters | Leveling: | Off |
| Numeric Format: | Engineering | Cable Compensation: 1 M Cable |  |
| Trigger Source: | External | Frequency Edit Type: Continuous |  |
| Source Impedance: | 25 ohms | Median: | Single Meas |
| RS-232 Baud Rate: | 9600 | Distortion: | Not tested |

### 2.5.1 Perform Calibration

This selection indicates the instruments expected calibration date and can be used to enter an open/short routine or to perform instrument calibration. The open/short (or zeroing process) automatically measures stray parameters and retains the data which are used to correct measurements so that the results represent parameters of the DUT alone without test lead or fixture effects. The cal routines, and when they should be used, are discussed in more detail below. The Quick cal routines can be performed much faster but are only applicable to the single test in which they are performed. Open/short data is deleted by going in and out of PROGRAM mode or programming any parameter of the current single test via remote. The operator is prompted by the 1920 display when performing the cal procedures.

## Parameter Selections:

Quick Short Cal Short zeroing at the currently programmed frequency only, Quick Open Cal

Quick Short/Open Cal

Short Cal

Open Cal
Short/Open Cal
Full Cal used if measurements are to be low impedance.
Open zeroing at the currently programmed frequency only, used if measurements are to be high impedance.
Both short and open zeroing at the currently programmed frequency only, used if measurements are to be over a wide range of impedance.
Short zeroing at all frequencies, used if measurements are to be low impedance.
Short zeroing at all frequencies, used if measurements are to be high impedance.
Both short and open zeroing at all frequencies, used if measurements are to be over a wide range of impedance.
This procedure will alter the calibration of the instrument and should only be used by qualified calibration personnel (with password entry). The proper calibration equipment is required to perform this procedure, see the Service and Calibration section of this manual for addition information.

The example below performs a quick open/short, other routines are similar with user prompting displayed on the instrument display.

| Right arrow key to skip | Cal with 1 M Cable Cal Due: 1/10/2001 | Indicates due date |
| :---: | :---: | :---: |
| Open/short and go to Keypad next annual calibration Lockout |  |  |
| or |  |  |
| - |  | Quick Short/Cal |
| Up or Down $\boldsymbol{\nabla}$ arrow key to select open/short calibration | Cal with 1 M Cable | Quick Open/Cal |
|  | Quick Short/Open Cal | Quick Short/Open Cal |
|  |  | Open Cal |
|  |  | Short/Op |
|  |  | Full Cal |

"Quick Cal" is not a choice if test is a Sequence (S1 thru S9)
"Open Cal" and "Quick Open Cal" are not a choice if test is a DC test (DCR, DCV, DCI)

Right arrow key to start calibration. Connect Open

Connect OPEN standard.
Press START to continue.

Press STOP at anytime to exit
Cal routine


Figure 2-4
Open Circuit Configuration (Kelvin Clip Lead Set or Test Fixture)

Press START to initiate
C: $1 \quad$ 9: F1 I5 V2
Open correction

C: $1 \quad$ 9: F1 I5 V2
Open correction


NOTE
During the open/short process these numbers should be changing.
A flashing fail light during the open/short process indicates an error has occurred.

## Remove Open, connect short

Connect SHORT standard. Press START to continue.


Figure 2-5
Short Circuit Configuration (Kelvin Clip Lead Set or Test Fixture)

Press START to initiate (DC Short Correction)

Press START to initiate (AC Short Correction)

| C: 1 9: F1 I5 V2 |
| :--- | :--- |
| Short correction |

Connect SHORT standard. Press START to continue.

| C: 1 9: F1 I5 V2 |
| :--- | :--- |
| Short correction |

Calibration Complete. Press START to continue.

Press START, unit returns to READY mode for testing or

| 1 Ls | Rs | 1.0000 KHz |
| :--- | :--- | :--- |
| 1.000 V | NoBias | Auto |

Press UTILITY key, then
Right arrow key to program other Utility functions

## NOTE

Quick short and open data are deleted by going in and out of PROGRAM mode or by programming any parameter of the current single test via remote.

The procedure for measuring the OPEN and SHORT corrections is optimized for fixtures and lead sets having a maximum uncompensated series impedance no greater than $50 \mathrm{~m} \Omega$ and a parallel (shunt) capacitance no greater than 5 pF . If a SHORT calibration is performed with a fixture having higher uncompensated resistance, the applied voltage will be automatically reduced during the calibration to keep the voltage across the fixture within range. The FAIL light will be lit to indicate that this is happening. Similarly, the applied voltage will be reduced as necessary during an OPEN calibration to keep the current within range for each frequency/range combination. However, measurement accuracy will be degraded on some ranges if the uncompensated series impedance is greater than $250 \mathrm{~m} \Omega$ or the parallel capacitance is greater than 25 pF .


### 2.5.2 Keypad Lockout

Selection of Off allows the operator to modify any stored test conditions and use all functions of the instrument, with no restrictions. When a password is entered for Lock Password only, the currently selected test conditions, along with the instrument START and STOP functions are active. This prevents an operator from modifying test conditions. When a password is entered for Lock Cycle Tests the test number selection (1 thru 30) is active using the Up or Down arrow keys allowing selection of any of the stored setups, however none can be modified.
Passwords consist of 6 digits, where the Left or Right arrow key is used to select one of six digits and the Up and Down arrow key is used to increase or decrease the digit. In the event of an unintentional lockout the password override is 242671.

## To Enable Lockout

 to change lockout function



Right | arrow key to |
| :--- |
| enter password |

| Keypad Lockout |
| ---: | ---: | ---: |
| $\underline{000000}$ | | Util |
| :---: |


| - |  |  |
| :---: | :---: | :---: |
| Up or Down $\boldsymbol{\nabla}$ arrow key to change the first digit (0 thru 9) | Keypad Lockout $\underline{800000}$ | Util |



Right arrow key to exit last digit


UTILITY key to exit and return to Ready mode.

To unlock Password
Press Utility key

| Keypad Lockout UR <br> On |
| :---: |
| Keypad Lockout Util <br> On With Test Number |
| Keypad Lockout Util <br> Enter Password to Unlock |

Right arrow key to
enter password

| - |  |  |
| :---: | :---: | :---: |
| Up or Down $\boldsymbol{\nabla}$ arrow key to change the first digit (0 thru 9) | $\begin{aligned} & \text { Keypad Lockout } \\ & \underline{800000} \end{aligned}$ | Util |



Right arrow key to exit last digit


Right arrow key to program next Utility function
or
UTILITY key to exit and return to Ready mode.

### 2.5.3 Display Type

Measured Parameters, Display is the measured values of both the primary and secondary, displayed with decimal point and units.
Deviation from Nominal, Display is the difference in measured value above or below (-) a programmed nominal value for the primary and secondary parameters. Refer to paragraph 2.3.10, programming the primary nominal and paragraph 2.3.12, programming the secondary display.
\% Deviation from Nominal, Display is the measurement in terms of a percent difference above or below (-) a programmed nominal value for the primary and secondary parameters. Refer to paragraph 2.3.10, programming the primary nominal and paragraph 2.3.12, programming the secondary nominal.

Up or Down $\boldsymbol{\Delta}$ arrow key to change display type


| Display Type |
| :---: | :---: |
| Dev. from Nominal |$\quad$ Util

Display Type Util \% Dev. from Nominal

Right arrow key to program
next Utility function
or
UTILITY key to exit and return to Ready mode.

Sample displays of measurement results are shown below for these three selections:


NOTE
It should be noted that if the parameter names are ever displayed as lower case, i.e. Is instead of Ls and df instead of DF, etc., it implies that the instrument does not have the proper calibration data stored for the cable compensation length being used ( 1,2 meters or no cable). To put this another way, the instrument is likely lacking some calibration data and is using "default" information rather than "real" calibration data.

### 2.5.4 Numeric Format

Allows selection from two different measurement results formats, Scientific or Engineering units. Scientific units are expressed as an exponent and engineering units are expressed in ohms for resistance, farads for capacitance, henries for inductance, etc. For example $e^{3}$ in scientific units can be expressed as $k \Omega$ in engineering units or $e^{-3}$ in scientific units can be expressed as $\mathrm{m} \Omega$ in engineering units, this is strictly user preference and convenience.

When scientific is selected the results will be displayed as some number of digits with decimal, exponent and units. When engineering units are selected the results will be displayed as some number of digits with decimal and units. The exception to this is that Q, DF, Phase and \%, are always displayed as fixed point numbers.

| Up or Down <br> to change format type | Numeric Format <br> Engineering |
| :--- | ---: |
|  |  |

Numeric Format
Scientific $\quad$ Util

Right - arrow key to program
next Utility function
or
UTILITY key to exit and return to Ready mode.

Format example:

Engineering

| 1 | Cs | 6.5040 nf |
| :--- | :--- | :--- |
| Bin 1 | DF | .000525 |

Scientific

| 1 | Cs $6.5040 \mathrm{e}-09 \mathrm{f}$ |
| :--- | :--- |
| Bin 1 | DF $5.2545 \mathrm{e}-04$ |

### 2.5.5 Trigger Source

This function allows the operator to select the measurement trigger mode between Internal or External. With trigger set for internal, once a start command is initiated (from front panel or remotely) the measurements will be repetitive and continually updated until a stop command is initiated. With trigger set for external a single measurement will be made once a start command is initiated (from front panel or remotely).
$\underset{\text { to change trigger source }}{\text { Up or Down }}$

## Trigger Source <br> Util <br> Internal

Trigger Source Util External

Right arrow key to program
next Utility function
or
UTILITY key to exit and return to Ready mode.

### 2.5.6 Source Impedance

This function allows the operator to select the 1920's output source impedance, selections available are $5, \mathbf{2 5}, \mathbf{5 0}$, and $\mathbf{1 0 0 \Omega}$. In general the measuring instrument's source impedance will usually have a direct effect on the measured impedance of the device. This is especially important when measuring the Q of a device and comparing the results between two different testers; in a true comparison the source impedance of the measuring instruments would be expected to be the same.


Right - arrow key to program next Utility function
or
UTILITY key to exit and return to Ready mode.

### 2.5.7 RS-232 Baud Rate

This function allows the operator to select the baud rate when communicating via the RS232 interface, selections possible include 9600, 19200, 9600 AutoReport, 19200 AutoReport or Disabled. The Auto Report options are used to log test results and error messages on a receive-only serial device, such as a serial printer. When set to Disabled the I/O port is non-functional, and the IEEE-488 port is functional.


Right arrow key to program
next Utility function
or
UTILITY key to exit and return to Ready mode.

### 2.5.8 IEEE-488 Address

This function allows the operator to select the IEEE-488 address, selections possible are $\mathbf{1}$ thru 16. The RS-232 interface must be set to Disable for the IEEE-488 interface to function.


Right - arrow key to program
next Utility function
or
UTILITY key to exit and return to Ready mode.

### 2.5.9 Clear All Tests

This selection allows the operator to clear all stored test setups in instrument memory ( 1 thru 30 for single tests or S1 thru S10 for sequential tests). After this operation, all tests are programmed to defaults coded by instrument software, which is generally as follows:

| Primary: | Ls | Range: | Automatic |
| :--- | :--- | :--- | :--- |
| Secondary: | Rs | Delay: | 0 |
| Frequency: | 1 kHz | No to Average: | 1 |
| Amplitude: | 1 V | Bin Type: | OFF |
| Accuracy: | High | Load Corr: | OFF |


| Up or Down <br> to select clear all tests | Clear All Tests <br> No | Util |
| :---: | :---: | :---: |
|  | Clear All Tests <br> Yes | Util |

Right $\downarrow$ arrow key to program
next Utility function
or
UTILITY key to exit and return to Ready mode.

### 2.5.10 Leveling

This function provides a constant voltage mode where the DUT is measured at an AC test voltage as determined by the programmable test parameter, Amplitude (refer to paragraph 2.3.4) When leveling is set for On, the instrument will adjust its output voltage to make the voltage across the DUT equal to the programmed test voltage. This will not be possible in all cases because the source impedance and DUT impedance form a voltage divider.


| Leveling |
| :---: |
| On |$\quad$ Util

Right - arrow key to program
next Utility function
or
UTILITY key to exit and return to Ready mode.

### 2.5.11 Cable Comp.

This function allows the operator to select the type connection made to the device under test, a direct connection to the front panel, No Cable, 1 M Cable or 2 M Cable. The 1920 is factory calibrated to compensate for the various lengths of test cables, choosing the correct cable length is important to assure accurate measurements. In addition to this, an open short circuit should be conducted any time the cable length is changed, refer to paragraph 2.5.1.


Right arrow key to program
next Utility function
or
UTILITY key to exit and return to Ready mode.

### 2.5.12 Freq. Edit Type

This function allows the operator to choose the test frequencies that will be available for selection, (refer to paragraph 2.3.3). Discrete, giving 16 possible frequencies and Continuous covering the entire frequency range from 20 Hz to 1 MHz .

When discrete is selected the 16 possible frequencies are:
$20,50,100,200,400,500 \mathrm{~Hz}, 1,2,5,10,20,50,100,200,500 \mathrm{kHz}$, and 1 MHz

Up or Down
to change frequency type
Freq. Edit Type
Discrete $\quad$ Util

Freq. Edit Type
Util
Continuous
Right - arrow key to program next Utility function
or
UTILITY key to exit and return to Ready mode.

### 2.5.13 Median

This function allows the operator to choose single or median measurement mode. When median of 3 is selected three individual measurements are made, the lowest and highest values are discarded and the median value displayed. Median mode can improve instrument accuracy by: specified accuracy/divided by $\sqrt{3}$; but never less than $0.1 \%$.
Up or Down
to change median
to change median

Right arrow key to program next Utility function

| Median |
| :--- | :--- |
| Single Meas. Util |

Median
Median of 3 $\quad$ Util
or
UTILITY key to exit and return to Ready mode.

### 2.5.14 Distortion

This function allows the operator to choose a distortion check during AC testing. When set to Check during AC test, the unit will detect distortion during a measurement and indicates the message "Signal Distorted" if this condition occurs. When set to Not tested, distortion will not be detected during a measurement.

Distortion is dependent on programmed test conditions, connection to the device, device impedance and is indicated when the current or voltage on the DUT at frequencies other than the test frequency is more than $2 \%$ of the signal at the test frequency. Distortion checking is generally the recommended test condition and is particularly important for high precision measurements where test leads could resonate with the device under test. Distortion may be best unchecked in a "noisy" environment or if the test voltage is below 100 mV .


| Distortion <br> Not tested | Util |
| :---: | :---: |

Distortion
Check during AC test

Right arrow key to program next Utility function
or
UTILITY key to exit and return to Ready mode.

### 2.5.15 Serial Number

This function allows the operator to view the instrument serial number. This serial number can also be returned when the unit is under remote control but there is no command for changing this number.

Serial Number
0104985

Right arrow key to program
next Utility function
or
UTILITY key to exit and return to Ready mode.

### 2.5.16 Software Version

This function allows the operator to view version of software installed in the instrument.

> Software Version Util

V1.32
UTILITY key to exit and return to Ready mode.

### 2.6 Error Messages

## Operator Help messages

Error in calibration
Watchdog timeout Consult factory
Measurement timed out Consult factory
Test voltage out of range; check for short
Calibration incomplete, Stopped by user
Out of range parameter value rcvd from remote
Invalid command received from the remote
Only the arrow keys are valid
Only the arrow and utility keys are valid
Only the arrow and program keys are valid
Invalid test set to default
Only the up and down arrow keys are valid
Only the start and stop keys are valid
Only up, down, and right arrow keys are valid
Only up, down, start and test keys are valid
Quick short/open valid only for single test

## Operator Help messages (continued)

DSP appears busy. Press STOP to clear
DSP did not take enough samples
Test is disabled program sequence test
DSP reported invalid params; check setup
Frequency and locked range incompatible
Locked range invalid for AC; set to HOLD
Primary nominal invalid Set to default
Secondary nominal invalid; set to default
Load correction invalid, for AUTO meas: disabled
Bin limits reset to defaults
Test restored from defaults correctly
Eeprom calibration defaults being set
Saving cal coefficients. Please wait
IEEE488 hardware not detected
Eeprom test/step data defaults being set
Eeprom misc data defaults being set
Eeprom cal kit data defaults being set
Eeprom lockout state default being set
Calibration measurement failed
Invalid calibration code
Cal kit data invalid. Please re-enter
Invalid cal state Contact factory
Invalid prog state Contact factory
Current bias invalid Compliance V exceeded
Current bias invalid Current source shutdown
Signal distorted: DUT is nonlinear
A/D current input ovrrng
A/D voltage input ovrrng
Unable to level applied voltage

## Instrument Error Messages

FATAL UNABLE TO WRITE, EEPROM CURRENT TEST/STEP
FATAL EEPROM CAL DATA, CANNOT BE INITIALIZED
FATAL EEPROM TEST DATA, CANNOT BE INITIALIZED
FATAL EEPROM MISC DATA, CANNOT BE INITIALIZED
EEPROM MISC CAL DATA, CANNOT BE INITIALIZED
FATAL INVALID MEAS, STATE HANDLER RETURN
DSP/HOST CODE MISMATCH, NEEDS DSP VERSION
FIRMWARE CRC ERROR, CONSULT FACTORY
FATEAL UNABLE TO WRITE, CALIBRATION DATA
GENERAL INTERNAL ERROR, CONSULT FACTORY

## Section 3: Interface

### 3.1 General

The 1920 Precision LCR Meter includes three interfaces standard with the unit, the Remote I/O , RS-232 and IEEE-488. Connection for these are located on the instrument's rear panel and discussed in detail below.

### 3.2 Remote I/O

The 1920 comes standard with an automatic component remote I/O interface port available through a 37 pin DB type connector located on the rear panel of the instrument. This port outputs signals to indicate a measurement in process and bin sorting judgments. It also has inputs for an external start and stop. All output lines are negative true from open-collector drivers that pull each signal line to a low voltage when that signal is active and let float when inactive. Each external line must be powered by a positive voltage between 5 and 24 V (max), with sufficient impedance (pull-up resistors implemented externally) to limit the active-signal (logic low) current to 20 mA (max).

The input signals are also active low and also requires a positive external voltage which must pull the signal down below 0.4 V (but not negative). For the inactive state (logic high), the external circuit must allow the signal line with its internal 3.3kohms to float above +2.5 V , but not above 5 V .


Figure 3-1
RS232 Remote I/O Pin Configuration

Table 3-1
Remote I/O Interface Connections

## Signal Name Pin Number Function

## Outputs:



Stop 18
Start

17

Stops the measurement in process
Starts the measurement

### 3.3 RS-232 Interface

An RS232 serial port interface is available on the 1920 through a 9 pin DIN connector on the rear panel of the instrument. The RS232 standard defines electrical specifications for the transmission of bit serial information. The use of the RS232 port requires three lines, receive data, transmit data, and signal ground. Refer to Figure 3-3 for null modem cable configuration to the standard db9 or db25 connector. Refer to Table 3-4 for the command set which also applies to the RS232 interface. Each command line must be terminated with a carriage return (CR) and line feed (LF) and multiple commands separated by a semicolon. Baud rate for the RS-232 interface is programmed through the UTILITY menu, refer to paragraph 2.5.7. Serial port parameters are comprised of 8 data bits, 1 stop bit, and no parity.


Figure 3-2
RS232 Interface Pin Configuration
Table 3-2
RS232 Interface Connections

Signal Name Pin Number Function

|  | Inputs: |  |  |
| :--- | :--- | :--- | :--- |
| DCD | 1 |  | Data Carrier Detect |
| DSR | 6 |  | Data Set Ready |
| RXD | 2 |  | Receive Data |
| CTS | 8 |  | Clear to Send |
| RI | 9 |  | Ring Indicator |
|  |  |  |  |
| RTS | 7 |  |  |
| TXD | 3 |  | Request to Send |
| DTR | 4 |  | Transmit Data |
| GND | 5 |  | Data Terminal Ready |
|  |  |  |  |

## db9 to db9 Cable Configuration

| 1920 |  |  | Controller |  |
| :--- | :--- | :---: | :--- | :--- |
| Pin \# | Function |  | Pin \# | Function |
| 2 | Receive data | Connect | 3 | Transmit data |
| 3 | Transmit data | to | 2 | Receive data |
| 4 | Data terminal ready |  | 6 | Data set ready |
| 5 | Signal ground |  | 5 | Signal ground |
| 6 | Data set ready |  | 4 | Data terminal ready |

db9 to db25 Cable Configuration

| 1920 |  |  | Controller |  |
| :--- | :--- | :---: | :--- | :--- |
| Pin \# | Function |  | Pin \# | Function |
| 2 | Receive data | Connect | 2 | Transmit data |
| 3 | Transmit data | to | 3 | Receive data |
| 4 | Data terminal ready |  | 6 | Data set ready |
| 5 | Signal ground |  | 7 | Signal ground |
| 6 | Data set ready |  | 20 | Data terminal ready |

## Figure 3-3

## RS-232 Cable Configurations

### 3.4 IEEE-488.2 Interface

### 3.4.1 General

An IEEE-488 interface is available standard on the 1920 through a connector ( 24 pin) on the rear panel. This interface can be used to connect to a system containing a number of instruments and a controller in which each meets IEEE Standard 488.2 (Standard Digital Interface for Programmable Instrumentation) Refer to Table 3-3 below for a full tabulation of connections and Table 3-4 for the command set.

The following functions have been implemented. Refer to the standard for an explanation of the function subsets, represented by the identifications below.

SH1 Source Handshake
AH1 Acceptor Handshake
T5 Talker
L3 Listener
SR1 Service Request
RL1 Remote Local

PP1 Parallel Poll
DC1 Device Clear
DT1 Device Trigger
C0 Controller
E2 Electrical Interface

### 3.4.2 IEEE-488 Connections

12


Figure 3-3
IEEE-488 Interface Pin Configuration
Table 3-3
IEEE-488 Interface Connections

| Signal Name Pin Number | Function |  |
| :--- | :--- | :--- |
| DAV | 6 | Low state: "Data is Available" and valid on DI01 <br> through DI08 <br> Low state: At least one listener on the bus is "Not <br> ready for Data". |
| NRFD 7 |  | Low state: At least one listener on the bus is "Not <br> Accepting Data". <br> "Attention" specifies 1 of 2 uses for the DI01 <br> through DI08 lines |
| NDAC | 8 | Low state - Controller command messages <br> High state - Data bytes from the talker device <br> "Interface Clear" |
| ATN | 11 | Low state - Returns portions of interface system to a <br> known quiescent state. <br> "Service Request" |
| SRQ | 10 | Low state - a talker or listener signals (to the <br> controller) need for attention in the midst of the <br> current sequence of events |
| REN | 17 | "Remote Enable" <br> Low state - enables each device to enter remote <br> mode when addressed to listen |
| EOI | 5 | High state - all devices revert to local control <br> "End of Identify" if ATN is in high state, then low <br> state of EOI indicates end of a multiple-byte data <br> transfer sequence. If ATN is in low state, then <br> low state of EOI activates a parallel poll. |

Table 3-3 (Continued) IEEE-488 Interface Connections

| Signal Name | Pin Number | Function |
| :--- | :--- | :--- |
| DI01 | 1 |  |
| DI02 | 2 | The 8-line data bus, which conveys interface |
| DI03 | 3 | messages (ATN low state) or device-dependent |
| DI04 | 4 | messages (ATN high state), such as remote- |
| DI05 | 13 | control commands from the controller or from a |
| DI06 | 14 | talker device |
| DI07 | 15 |  |
| DI08 | 16 |  |

### 3.4.3 IEEE-488 and RS-232 Commands

## Table 3-4

IEEE \& RS-232 Commands
Command
Function
Parameter(s)
SAVE SAVE Save changes entered by remote since power-up.

| NOTE |
| :---: |
| Command must be entered twice. If not done, changes will be lost on power cycle. |

## TEST:

| TEST | Set test number | nn |
| :--- | :--- | :--- |
| STEP | Set step number | n |
| SEQuence | Set sequence test number | n |

## NOTE

CONFigure or SYSTem commands that follow should only be used with the commands for which they were intended. The 1920 commands are interpreted as numeric values but for convenience in programming they are not entered as numeric but rather as a more understandable command. For example; when programming the primary parameter for Lp it would appear as "CONF: PPAR LP", which is also equivalent to "CONF: PPAR 2". It is possible to create a command that appears wrong but will not generate any error message. If the command was "CONF: PPAR DPCT", the primary parameter would still be Lp because DPCT is interpreted as a numeric value of 2 , even though it's a subset of an entirely different command (subset of DISPlay). To eliminate any confusion always use the subset commands in conjunction with those listed in this table.

Table 3-4 (Continued) IEEE \& RS-232 Commands

Command
Function
Parameter(s)

| CONFigure: |  |  |
| :--- | :--- | :--- |
| PPARameter | Set primary parameter | AUTO LS LP RS RP |
|  |  | CS CP DF Q Z Y P |
|  |  | ESR GP XS BP V I |
| SPARameter | Set secondary parameter | DCV DCR DCI |
|  |  | NONE LS LP RS |
|  |  | RP CS CP DF Q Z Y |
|  |  | P ESR GP XS BP V I |
| FREQuency | Set test frequency in Hz | DCV DCR DCI |
| APPLV | Set test voltage in V (rms if AC) | nnn |
| BIAS | Set bias voltage in V | OFF n.nnn |
| RANGe | Select range | AUTO HOLD nn |
| MACracy | Set measurement accuracy | LOW MEDIUM |
|  |  | HIGH LND |


| When programmed for Low No Display (LND), measurement data is not available via IEEE-488 or RS-232 |
| :--- | :--- | :--- |
| interfaces, but only available as binning data through the Remote I/O interface |$|$|  |  | nnn.n |
| :--- | :--- | :--- |
| TDElay | Set delay time in S | nnn |
| AVERage | Set count to average | MEAS n.nnn |
| PNOMinal | Set the nominal value of primary meas |  |
|  |  | NONE PCTdev |
| BINning | Set binning type | ABSolute |
|  |  | nn.nnn |
| HIGh | Set high limit in mA | \#\# n.nn |
| PHIDEV | Set primary bin\#\# high limit to n.nnn | \#\# n.nn |
| PLODEV | Set primary bin\#\# low limit to n.nnn | n.nnn |
| SNOMinal | Set nominal value of secondary meas | n.nnn |
| SHIDEV | Set secondary parameter high limit | n.nnn |
| SLODEV | Set secondary parameter low limit | OFF ON MEAS |
| LOADcorr | Set load correction | n.nnn |
| PLOAD | Set primary load correction | n.nnn |
| SLOAD | Set secondary load correction |  |

## Table 3-4 (Continued)

## IEEE \& RS-232 Commands

Command
SEQuence:
TEST

SYSTEM:
LOCKout
DISPlay
FRESult
TRIGger
SRCImp
LEVELing
CABLecomp
DISCrete

DISTortion
MEDIAN
CALibrate
DATE

## VIEW:

TEST?: View the test program parameters
TEST View the single-test's parameters
SEQuence View the sequence
The format of the returned data is as follows:
Step 1: Test<tab.nn or Fn or skip or none><CR>
Step 2: Test<tab.nn or Fn or skip or none><CR>
Continued through Step 6
UTILity?
LOCKout?

STOP

View the utilities programmed
View the lockout state
Stops a measurement
nn
n
nn NONE SKIP

OFF ON
DMEAS DDEV
DPCT
SCI ENG
EXT INT
n(0-3)
OFF ON
n(0-3)
OFF(discrete)
ON(cont)
OFF ON
OFF ON
FULL SHORt OPEN
QUIckos
nn nn nnnn
Parameter(s)
ne

## Table 3-4 (Continued)

 IEEE \& RS-232 CommandsCommand
Function
Parameter(s)
MEASure
Triggers a measurement of the selected type. If sequence is enabled this command will trigger those type of measurements also. The result type is set by the display type parameter

M?
Triggers a measurement of the selected type, and automatically returns the answer after the measurement is complete. This command is a faster way to implement the sequence "MEAS; *WAIT; FETCH?". The response is status, Pri, Sec. (Status $0=$ good, Status $1=$ no good)
If sequence is enabled this command will trigger those type of measurements also. The result type is set by the display type utility (and by the measurement ACCURACY setting, if LOW NO DISPLAY is selected.)

FETCh?
Fetches the most recent measurement results. The reply is a copy of the LCD screen, with the following exceptions:

The ohms, degrees, and micro symbols are replaced by "ohm", "deg', or "u"
Each group of one or more spaces is replaced with one tab character (ASCII 9)
Each line of the display is followed by CRLF
For a sequence test, the results of each test which has been performed are reported

If TRIGGER is set for INTERNAL the results of the last measurement are reported. For a sequence test, results from the later steps in the sequence may have been measured on the previous pass through the sequence

When accuracy is selected to LOW, NO DISPLAY, there is no choice of display format, and the data will be returned as follows:

NOTE: Response includes load correction as noted for given accuracy

| Accuracy: | Fetch?: | $\underline{\text { M?: }}$ |
| :--- | :--- | :--- |
| High | Yes | Yes |
| Medium | Yes | No |
| Low | Yes | No |

Table 3-4 (Continued)
IEEE \& RS-232 Commands

Command Function Parameter(s)

If the secondary parameter is set to NONE, the format will be:
n.nnnnEmmm<space>*<space>

If the secondary parameters is set to anything other than NONE, the format will be:
n.nnnnEmmm<space> n.nnnnEmmm <space>

If the measurement is invalid for some reason (typically an A/D overrange, because normally the range will be locked to shorten the cycle time), the return format will be:

No<tab>Data
ERRMSG? When error messages are presented on the front panel, they are also logged in a 16-deep queue, and the device-dependent error bit is set in the ESR. The response to this query consists of the text of each error message in the log, with each line followed by <CRLF>, and and additional <CRLF> after the last message. The queue is cleared by sending ERRMSG?, *RST, or *CLS.

SUMMary? $\quad$ When test is a single step test
Read bin summary. If bin is enabled format will be:
$\mathrm{nn}<\mathrm{tab}>\mathrm{h}$.hhhehh $<$ tab $>1$. 111 le ll<tab>cccc<CRLF>
Where nn is the bin number, h and 1 are digits of the high and low limits, and c the digits of the bin count (primary units for bins 1-10 and secondary units for bin 11). Numeric limits for bins 12-14 will always return 0 , since these bins do not have independent limits

If bin is disabled format will be:
nn<tab>Disabled<tab><tab>
If all primary bins are disabled, Bin 1 is used to count devices which pass secondary limits and will be returned as:

1 <tab>Both Pass<tab><tab>cccc
When test is a sequence test, format will be
$1<$ tab>PassAllSteps<tab><tab>cccc
nn<tab>FailStepm<tab><tab>cccc
Where nn is bin numbers 2 through 7 and m is the corresponding test number, which is (nn-1).

Table 3-4 (Continued)
IEEE \& RS-232 Commands
Command
Function
Parameter(s)

## NOTE

Bin limits are always returned as absolute deviation even if bin type is \% deviation. This is a convenient way to see what the actual limits will be when setting up a test
*IDN?
*ESR?
*STB?
*ESE?
*SRE?
*ESE
*SRE
*RST
*TST
*CLS
*OPC

* OPC?
*WAIT

Returns instrument identification "QuadTech, 1920,xx...xx, software version". x denotes serial number up to 8 digits

Returns the read of the event status register.
Returns the read of the status byte register.
Returns the read of the event status enable register.
Returns the read of the service request enable register.
Set the event status enable register value
Set the service request enable register. value
Reset the common buffers
Self test query
Clear standard event status register
Operation complete
Is operation complete
Wait until operation is complete before executing next command

### 3.4.4 Formats

IEEE 488.2 enable remote programming of all instrument functions, measurement conditions and comparator settings etc. Outputs include measurement conditions, open corrections, and measured values.

## Data Formats

Data will be transmitted in ASCII NR3 format per IEEE488.2 sec. 8.7.4 and reproduced below.

## Multiple results

All response messages will be terminated by the NL character together with the EOI line asserted.

## Status Byte Register

| $\frac{\text { Bit }}{7}$ | Decimal <br> Value | 128 |
| :--- | :--- | :--- |$\quad$| Use |
| :--- |
| 6 |

*The Status Byte Register is readable via the standard *STB? as defined in paragraph. 11.2.2.2 of the IEEE spec. The 1920 will also implement an SRE register to enable each bit of the Status Byte Register per paragraph 11.3.2 of the IEEE spec. This register shall be readable by a SRE? command and writeable by a SRE <\#> command.

Standard Event Status Register
Decimal

| $\frac{\text { Bit }}{7}$ | $\frac{\text { Value }}{}$ | 128 |  |
| :--- | :--- | :--- | :--- |
| 6 | 64 | Use |  |
| 6 | 32 | Power Up Since Last Query |  |
| 5 | 16 | None |  |
| 4 | 8 | Command Error (Syntax) |  |
| 3 | 4 | Execution Error (Over Range, etc.) |  |
| 2 | 2 | None |  |
| 1 | 1 | Query Error |  |
| 0 |  | None |  |

This register is read by executing an "*ESR?" command per paragraph 11.5.1.2.2 (except no *). Note that this is a destructive read. Reading the register clears it. Each bit of the Event register must be enabled in order to cause the ESB bit of the Status Register to be set. This enabling is done in the Standard Event Status Enable Register by issuing an ESE command per paragraph 11.5.1.3.

## Section 4: Theory

### 4.1 Introduction

The model 1920 Precision LCR Meter uses a principle of measurement which is based upon a technique developed by QuadTech for its 7000 Series of Precision LCR Meters. In particular, the model 1920 employs digital techniques for signal generation and detection, as well as for the more usual data processing, user input output and remote communications functions. The following section provides a general overview of the model 1920 measurement technique for one familiar with impedance measurement and modern instrumentation. Subsequent sections provide detailed descriptions of operation, circuit block diagrams and system level control signals.

### 4.1.1 Description of 1920 Precision LCR Meter

In the model 1920 Precision LCR Meter, the voltage across the device under test (DUT) is measured, and the current through the DUT is measured across a reference resistor Rs which carries substantially the same current. The voltage across the DUT is Ex and the voltage across Rs is Es. Both voltages are sampled many times per cycle of the applied sine wave excitation. Ex and Es are essentially simultaneously sampled. There are five reference resistors in the 1920; the one used for a particular measurement is the optimal resistor for the device under test, frequency and amplitude of excitation. These characteristics are stored in the 1920 in non-volatile memory.

For both Ex and Es a real and imaginary (in phase and quadrature) component are computed mathematically from the individual sample measurements. The real and imaginary components of Ex and Es are with respect to a reference of arbitrary phase, so that by themselves they are meaningless. Any differences in the voltage and current detection and measurement process, as well as non-idealities in the sampling and digitization process, are corrected via software using calibration data. The real and imaginary components of $E x\left(E x_{r}\right.$ and $\left.E x_{i}\right)$ are combined with the real and imaginary components of $\mathrm{Es}^{\left(\mathrm{Es}_{r} \text { and } \mathrm{Es}_{\mathrm{i}}\right) \text { and the known characteristics of the reference resistor to }}$ determine the apparent complex impedance of the DUT using complex arithmetic.
Further calculations are made to remove the characteristics of the test fixture ("stray" capacitance and conductance and series resistance and inductance) if simple SHORT and OPEN calibration measurements have been made by the operator. These corrections are stored in non-volatile memory in the 1920 and are retained during power down and power up.

The detection and excitation circuitry is configured for each measurement by an embedded computer. For the excitation circuitry this includes frequency of excitation, DC bias current, and excitation level. Frequency is varied from 20 Hz to 1 MHz . Excitation level is between 20 mV and 1 V (open circuit).

For the detection circuitry this includes the reference resistor, the gain in the current and voltage detectors, and analog filtering optimized for the frequency of excitation. There are five reference resistors, each of which covers an impedance range of $15: 1$, and $5: 1$ at the lowest impedance. The reference resistor is normally chosen by the embedded computer to match the impedance of the unknown as closely as possible. However, the user may override this function, which can improve measurement speed in specialized applications. Gain in the voltage detector and current detector is normally chosen by the embedded computer to optimize the performance of the digitization process. The optimum gain in both detectors depends on excitation level, frequency and DUT impedance. As with the reference resistor, this can be overridden by the user.

The embedded computer also controls measurement speed. There are three settings for measurement accuracy: High (1 measurement per second), Medium (10 Measurements per second), and Low ( 40 measurements per second). These times can be lengthened somewhat depending on the frequency of excitation, averaging, median, and other conditions. The embedded computer also controls the local user interface (keyboard and display), and the remote interfaces (RS-232, IEEE-488 and handler interface).

A separate Digital Signal Processor (DSP) performs the high-speed calculations inherent in the measurement technique. The DSP computes the real and imaginary components of impedance, and converts these into Capacitance (Cs/Cp), Inductance (Ls/Lp), Resistance (Rs/Rp), Dissipation (DF) and Quality (Q) Factors, Impedance (|Z|), Admittance |Y|, Phase Angle ( $\theta$ ), Equivalent Series Resistance (|ESR|), Conductance (Gp), Reactance (Xs), Susceptance ( Bp ). Any two parameters can be measured and displayed simultaneously. In the above parameters the subscript s denotes series equivalent circuit, while subscript p denotes parallel equivalent circuit.

### 4.1.2 Block Diagram

The block diagram, Figure 4-1, shows the embedded computer connected via a CPU bus (B) composed of address, control and data lines to the other major functional blocks of the circuit.

The embedded computer includes the following types of memory: RAM for Program execution, FLASH for non-volatile program storage, EEROM for storage of calibration data, instrument configuration, and test setups.

The basic sine wave for excitation is generated in block (C). The embedded computer loads two values into block (C). The first value sets the basic frequency of the sine wave. The second value sets the frequency of the sampling pulse. The frequency of the sampling pulse is harmonically related to that of the sine wave. The generation process is described in section 4.2.2.

The sine wave is fed from block (C) to block (D), the power buffer. The embedded computer configures the power buffer to control the excitation level and voltage/current mode.

The final manipulation of the excitation signal is in block (E), bias control. The bias control block superimposes the AC excitation on a programmable DC bias current. The output of block ( E ) is connected to the IH terminal in section F for connection to the DUT.

Block (F), in addition to the IH line described above, contains three other coaxial connections to the DUT. PH and PL are the connections across the DUT that are used to measure the voltage across the DUT. IL is the connection that sinks the current sourced by IH. The current into IL is essentially exactly that in the DUT; the PH and PL connections are to high impedance circuitry and draw very little current. Any departure from ideal behavior is calibrated out digitally during the calibration process.

Block (G) is the circuitry which senses current and voltage and amplifies these signals for later processing. These signals are converted into digital streams of readings in block (H). In addition to the two analog signals from the voltage and current detectors, block $(\mathrm{H})$ also has a sampling pulse signal that synchronizes the digitization process with the sine wave signal. The sampling pulse is generated in block (C). The digital stream of readings is fed into block (I) where they are combined to produce complex impedance, which is communicated to the embedded computer.


Figure 4-1
1920 Instrument Block Diagram

### 4.2 Principal Functions

### 4.2.1 Fundamental Measurement

The fundamental measurement technique is illustrated as a simplified diagram in Figure 4-2. A sine wave generator drives current IH through the DUT and a standard resistor in series. Two differential amplifiers with controlled gains produce voltages Ex and Es. Simple algebra results in an expression for the complex impedance.
$\mathbf{Z x}=\mathbf{R s} *(\mathbf{E x} / \mathbf{E s})$


Figure 4-2
Fundamental Measurement
Notice that this ratio is complex. The embedded computer converts from the complex impedance Zx to any of the available parameters, for example C and DF , mathematically.

### 4.2.2 Sine Wave and Sampling Pulse Generation

The direct digital sine wave synthesizer chips increment the phase of two sine waves internally at each clock cycle. The two sine wave signals are output from the chips differential analog signals. One of the outputs is as the signal source. The other output is filtered (low-pass) and connected to the comparator input of the DDS to create a sampling clock. The two phase increments are chosen so that the sampling pulse is in proper relationship with the sine wave.

### 4.2.3 Digitization

The digitization section consists of a simultaneously sampling two-channel analog to digital converter. The two samples are taken very nearly at the same time. Any delay of one channel relative to the other is calibrated out digitally during the calibration process.

Figures 4-3, 4-4 and 4-5 further illustrate the signal flow and test points within the 1920 Precision LCR Meter.


Figure 4-3
Signal Generation


Figure 4-4
Detector Circuits


Digital Signal Processor

## Section 5: Service \& Calibration

### 5.1 General

Our warranty (at the front of the manual) attests the quality of materials and workmanship in our products. If malfunction should be suspected, or other information be desired applications engineers are available for technical assistance. Application assistance is available in the U.S. by calling 978-461-2100 and asking for Applications Support. For support outside of the United States please contact your local QuadTech distributor.

### 5.2 Instrument Return

Before returning an instrument to QuadTech for service please call our Customer Care Center (CCC) at 800-253-1230 for return material authorization (RMA). It will be necessary to include a Purchase Order Number to insure expedient processing, although units found to be in warranty will be repaired at no-charge. For any questions on repair costs or shipment instructions please contact our CCC Department at the above number. To safeguard an instrument during storage and shipping please use packaging that is adequate to protect it from damage, i.e., equivalent to the original packaging and mark the box "Delicate Electronic Instrument". Return material should be sent freight prepaid, to:

QuadTech, Inc.
5 Clock Tower Place, 210 East
Maynard, MA 01754
Attention: RMA \#

Shipments sent collect can not be accepted.

### 5.3 Calibration

Calibration of the 1920 LCR Meter is completed at the factory and includes a NIST calibration certificate. Verification of instrument operation and accuracy is recommended on an annual basis. Accurate operation of the 1920 instrument is confirmed using the following verification procedure.

### 5.3.1 1920 Verification Procedure

This section outlines the relevant information to verify performance of the 1920 LCR Meter. It is recommended that performance be performed at least once a year using this outline procedure.
Instrument should be warmed up for a minimum of 15 minutes prior to verification. Verification should be performed under the following conditions: Temperature equal to $23^{\circ} \mathrm{C} \pm 1.2^{\circ} \mathrm{C}$ and Relative Humidity ( RH ) between $35 \%$ and $55 \%$.

Recommended standards are listed below. All standards should be traceable to a National Laboratory such as N.I.S.T. with calibrated values for primary and secondary parameters at the required test frequencies. QuadTech's verification conforms to ANSI Z540 and QuadTech recommends that the calibrated values for the primary and secondary standards have an uncertainty 4 times better than the primary and secondary accuracy specified in the Verification Data Sheet. If the calibrated values for the standards used do not have an uncertainty of 4 times better than the specified accuracy of the 1920 the uncertainty of the standard should be added to the specified accuracy of the 1920. For example: if the calibrated value of the $500 \mathrm{~m} \Omega$ standard is $495.0 \mathrm{~m} \Omega \pm 1 \%$ at 1000 Hz , the expected reading on the 1920 would be $495.0 \mathrm{~m} \Omega \pm 1.327 \%$ ( $1 \%$ for the standard accuracy plus $0.327 \%$ for the 1920 accuracy). This also applies for secondary parameters as well.

Primary and secondary accuracy specifications given in the Verification Data Sheet are based upon the accuracy formulas in section 2.3.7 of this manual.

## Measurement Standards

Inductance Standards 4 Terminal

| Inductor | $10 \mu \mathrm{H}$ (nominal value) |
| :--- | :--- |
| Inductor | $100 \mu \mathrm{H}$ (nominal value) |
| Inductor | $1000 \mu \mathrm{H}$ (nominal value) |

## Standard Open and Short

## Resistance Standards 4 Terminal

| Resistor | 95 K ohm (nominal value) |
| :--- | :--- |
| Resistor | 6 K ohm (nominal value) |
| Resistor | 374 ohm (nominal value) |
| Resistor | 25 ohm (nominal value) |
| Resistor | 500 m ohm (nominal value) |


| Capacitance | Standards 2 or 4 Terminal |
| :--- | :---: |
| Capacitor | 50 pF (nominal value) |
| Capacitor | 100 pF (nominal value) |
| Capacitor | 200 pF (nominal value) |
| Capacitor | 500 pF (nominal value) |
| Capacitor | 1000 pF (nominal value) |
| Capacitor | $0.1 \mu \mathrm{~F}$ (nominal value) |
| Capacitor | $0.05 \mu \mathrm{~F}$ (nominal value) |
| Capacitor | $0.02 \mu \mathrm{~F}$ (nominal value) |
| Capacitor | $0.01 \mu \mathrm{~F}$ (nominal value) |
| Capacitor | $0.002 \mu \mathrm{~F}$ (nominal value) |

## Measurement Procedure

The 1920 should be set to the following:
[TEST CONDITIONS]
Parameter $=$ Automatic
Frequency $=$ Selected per data sheet below
Amplitude $=1$ Volt
Bias Voltage = Off
Measure Range = Auto
Accuracy = High
Delay $=$ Off
Averaging = 1
Binning $=$ Off
[UTILITY FUNCTIONS]
Trigger Source = External
Source Impedance $=25$ ohms
Cable Compensation $=1 \mathrm{M}$
Frequency Edit Type = Continuous
Connections to all standards should be via a 1-meter cable.
A multiple frequency open and short correction should be performed prior to any measurements. See paragraph 2.5.1 for information on performing an open and short correction.

Connect each standard listed in the Verification Data Sheet and select the test frequency on the 1920 as listed, see paragraph 2.3.3. Record the results in the Verification Data Sheet.

### 5.3.2 1920 Verification Data Sheet

R500M

| Freq | Pri. Actual | Sec. Actual | Voltage | Primary Meas. | Sec. Meas. | Pspec | Sspec |
| ---: | :--- | :---: | :---: | :--- | :--- | :--- | :--- |
| 1000 |  |  | 1 |  |  | $0.327 \%$ | 0.0033 |
| 10000 |  |  | 1 |  |  | $0.327 \%$ | 0.0033 |
| 100000 |  |  | 1 |  |  | $0.460 \%$ | 0.0047 |

R25

| Freq | Pri. Actual | Sec. Actual | Voltage | Primary Meas. | Sec. Meas. | Pspec | Sspec |
| ---: | :--- | :--- | :---: | :--- | :--- | ---: | ---: |
| 1000 |  |  | 1 |  |  | $0.120 \%$ | 0.0012 |
| 100000 |  |  | 1 |  |  | $0.166 \%$ | 0.0017 |
| 1000000 |  |  | 1 |  |  | $0.644 \%$ | 0.0065 |

R374

| Freq | Pri. Actual | Sec. Actual | Voltage | Primary Meas. | Sec. Meas. | Pspec | Sspec |
| ---: | :--- | :--- | :---: | :--- | :--- | :--- | :--- |
| 1000 |  |  | 1 |  |  | $0.116 \%$ | 0.0012 |
| 100000 |  |  | 1 |  |  | $0.163 \%$ | 0.0016 |
| 1000000 |  |  | 1 |  |  | $0.761 \%$ | 0.0076 |
|  |  |  |  |  |  |  |  |

R6K

| Freq | Pri. Actual | Sec. Actual | Voltage | Primary Meas. | Sec. Meas. | Pspec | Sspec |
| ---: | :--- | :--- | :---: | :--- | :--- | :--- | :--- |
| 1000 |  |  | 1 |  |  | $0.117 \%$ | 0.0012 |
| 10000 |  |  | 1 |  |  | $0.117 \%$ | 0.0012 |
| 100000 |  |  | 1 |  |  | $0.196 \%$ | 0.0020 |

R95.3K

| Freq | Pri. Actual | Sec. Actual | Voltage | Primary Meas. | Sec. Meas. | Pspec | Sspec |
| ---: | :--- | :--- | :---: | :--- | :--- | ---: | ---: |
| 100 |  | 1 |  |  | $0.196 \%$ | 0.0020 |  |
| 1000 |  | 1 |  |  | $0.141 \%$ | 0.0014 |  |
| 10000 |  | 1 |  |  | $0.141 \%$ | 0.0015 |  |

L10uH

| Freq | Pri. Actual | Sec. Actual | Voltage | Primary Meas. | Sec. Meas. | Pspec | Sspec |
| ---: | :--- | :--- | :---: | :--- | :--- | :--- | :--- |
| 10000 |  |  | 1 |  |  | $0.384 \%$ | 10.2285 |
| 100000 |  |  | 1 |  |  | $0.197 \%$ | 37.8456 |
| 1000000 |  |  | 1 |  |  | $0.679 \%$ | 5.8232 |

L100uH

| Freq | Pri. Actual | Sec. Actual | Voltage | Primary Meas. | Sec. Meas. | Pspec | Sspec |
| ---: | :--- | :--- | :---: | :--- | :--- | :--- | :--- |
| 1000 |  |  | 1 |  |  | $0.335 \%$ | 0.372 |
| 100000 |  |  | 1 |  |  | $0.207 \%$ | 60.2616 |
| 1000000 |  |  | 1 |  |  | $1.039 \%$ | 66.2351 |

## L1000uH

| Freq | Pri. Actual | Sec. Actual | Voltage | Primary Meas. | Sec. Meas. | Pspec | Sspec |
| ---: | :--- | :--- | :---: | :--- | :--- | :--- | :--- |
| 1000 |  |  | 1 |  |  | $0.477 \%$ | 0.2389 |
| 10000 |  |  | 1 |  |  | $0.161 \%$ | 5.0163 |
| 100000 |  |  | 1 |  |  | $0.177 \%$ | 55.2771 |

C50pF

| Freq | Pri. Actual | Sec. Actual | Voltage | Primary Meas. | Sec. Meas. | Pspec | Sspec |
| ---: | :--- | :--- | :---: | :--- | :--- | :--- | :--- |
| 1000 |  |  | 1 |  |  | $0.959 \%$ | 0.0109 |
| 100000 |  |  | 1 |  |  | $0.352 \%$ | 0.0084 |
| 1000000 |  |  | 1 |  |  | $1.889 \%$ | 0.1029 |

C100pF

| Freq | Pri. Actual | Sec. Actual | Voltage | Primary Meas. | Sec. Meas. | Pspec | Sspec |
| ---: | :--- | :--- | :---: | :--- | :--- | :--- | :--- |
| 1000 |  |  | 1 |  |  | $0.536 \%$ | 0.0061 |
| 100000 |  |  | 1 |  |  | $0.256 \%$ | 0.0060 |
| 1000000 |  |  | 1 |  |  | $1.248 \%$ | 0.0678 |

C200pF

| Freq | Pri. Actual | Sec. Actual | Voltage | Primary Meas. | Sec. Meas. | Pspec | Sspec |
| ---: | :--- | :--- | :---: | :--- | :--- | :--- | :--- |
| 1000 |  |  | 1 |  |  | $0.326 \%$ | 0.0037 |
| 100000 |  |  | 1 |  |  | $0.208 \%$ | 0.0049 |
| 1000000 |  |  | 1 |  |  | $0.930 \%$ | 0.0504 |

C500pF

| Freq | Pri. Actual | Sec. Actual | Voltage | Primary Meas. | Sec. Meas. | Pspec | Sspec |
| ---: | :--- | :--- | :---: | :--- | :--- | :--- | :--- |
| 1000 |  |  | 1 |  |  | $0.200 \%$ | 0.0023 |
| 100000 |  |  | 1 |  |  | $0.179 \%$ | 0.0042 |
| 1000000 |  |  | 1 |  |  | $0.739 \%$ | 0.0400 |

## C1000pF

| Freq | Pri. Actual | Sec. Actual | Voltage | Primary Meas. | Sec. Meas. | Pspec | Sspec |
| ---: | :--- | :--- | :---: | :--- | :--- | :--- | :--- |
| 1000 |  |  | 1 |  |  | $0.158 \%$ | 0.0018 |
| 100000 |  |  | 1 |  |  | $0.170 \%$ | 0.0040 |
| 1000000 |  |  | 1 |  |  | $0.677 \%$ | 0.0366 |

C2nF

| Freq | Pri. Actual | Sec. Actual | Voltage | Primary Meas. | Sec. Meas. | Pspec | Sspec |
| ---: | :--- | :--- | :---: | :--- | :--- | ---: | ---: |
| 1000 |  |  | 1 |  |  | $0.137 \%$ | 0.0015 |
| 100000 |  |  | 1 |  |  | $0.165 \%$ | 0.0038 |
| 1000000 |  |  | 1 |  |  | $0.649 \%$ | 0.0351 |

## C10nF

| Freq | Pri. Actual | Sec. Actual | Voltage | Primary Meas. | Sec. Meas. | Pspec | Sspec |
| ---: | :--- | :--- | :---: | :--- | :--- | :--- | :--- |
| 1000 |  |  | 1 |  |  | $0.120 \%$ | 0.0014 |
| 100000 |  |  | 1 |  |  | $0.162 \%$ | 0.0038 |
| 1000000 |  |  | 1 |  |  | $0.654 \%$ | 0.0354 |

## C20nF

| Freq | Pri. Actual | Sec. Actual | Voltage | Primary Meas. | Sec. Meas. | Pspec | Sspec |
| ---: | :--- | :--- | :---: | :--- | :--- | :--- | :--- |
| 1000 |  |  | 1 |  |  | $0.118 \%$ | 0.0013 |
| 100000 |  |  | 1 |  |  | $0.162 \%$ | 0.0038 |
| 1000000 |  |  | 1 |  |  | $0.689 \%$ | 0.0373 |

C50nF

| Freq | Pri. Actual | Sec. Actual | Voltage | Primary Meas. | Sec. Meas. | Pspec | Sspec |
| ---: | :--- | :--- | :---: | :--- | :--- | :--- | :--- |
| 1000 |  |  | 1 |  |  | $0.116 \%$ | 0.0013 |
| 100000 |  |  | 1 |  |  | $0.165 \%$ | 0.0038 |
| 1000000 |  |  | 1 |  |  | $0.802 \%$ | 0.0436 |

C100nF

| Freq | Pri. Actual | Sec. Actual | Voltage | Primary Meas. | Sec. Meas. | Pspec | Sspec |
| ---: | :--- | :--- | :---: | :--- | :--- | :--- | :--- |
| 1000 |  |  | 1 |  |  | $0.116 \%$ | 0.0013 |
| 100000 |  |  | 1 |  |  | $0.170 \%$ | 0.0040 |
| 1000000 |  |  | 1 |  |  | $0.998 \%$ | 0.0545 |

### 5.3 Diagnostics

### 5.3.1 Start-up Diagnostics

On start-up the unit displays step numbers during the initialization process. Should the display stop during this initialization the number displayed serves as a diagnostic tool. The numbers correspond to the following functions:
(1) Verifies (initializes if necessary) cal data corresponding to No Cable (direction connection to the front panel.
(2) Verifies (initializes if necessary) cal data corresponding to 1 M Cable.
(3) Verifies (initializes if necessary) cal data corresponding to 2 M Cable.
(4) Verifies (initializes if necessary) calibration kit data.
(5) Verifies (initializes if necessary) test and step values.
(6) Verifies (initializes if necessary) Utility setting and password.
(7) Verifies (initializes if necessary) single tests.
(8) Verifies (initializes if necessary) multi tests.
(9) Booting the Digital Signal Processor (DSP)
(10) Initialization complete

In case a problem should occur with the front panel display the Remote I/O bin outputs (1 thru 10) are also activated during this initialization process. Refer to paragraph 3.2 for the pin out of Bins 1 through 10.


[^0]:    WARNING
    Potentially dangerous voltages may be present on front and rear panel terminals．Follow all warnings in this manual when operating or servicing this instrument．Dangerous levels of energy may be stored in capacitive devices tested by this unit．

